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Maximum Likelihood Estimation of the Latent Class Model through Model Boundary Decomposition

Elizabeth S. Allman[1], Hector Baños[1], Robin Evans[2], Serkan Hoşten[3,*], Kaie Kubjas[4,5,6], Daniel Lemke[7], John A. Rhodes[1], Piotr Zwiernik[8]

[1] *Department of Mathematics and Statistics, University of Alaska Fairbanks, Fairbanks, USA*
[2] *Department of Statistics, University of Oxford, Oxford, UK*
[3] *Department of Mathematics, San Francisco State University, San Francisco, USA*
[4] *Laboratoire d'Informatique, Sorbonne Université, Paris, France*
[5] *Laboratory for Information & Decision Systems, MIT, Cambridge, USA*
[6] *Department of Mathematics and Systems Analysis, Aalto University, Aalto, Finland*
[7] *Synopsis, Mountain View, USA*
[8] *Department of Economics and Business, Universitat Pompeu Fabra, Barcelona, Spain*

Abstract. The Expectation-Maximization (EM) algorithm is routinely used for maximum likelihood estimation in latent class analysis. However, the EM algorithm comes with no global guarantees of reaching the global optimum. We study the geometry of the latent class model in order to understand the behavior of the maximum likelihood estimator. In particular, we characterize the boundary stratification of the binary latent class model with a binary hidden variable. For small models, such as for three binary observed variables, we show that this stratification allows exact computation of the maximum likelihood estimator. In this case we use simulations to study the maximum likelihood estimation attraction basins of the various strata and performance of the EM algorithm. Our theoretical study is complemented with a careful analysis of the EM fixed point ideal which provides an alternative method of studying the boundary stratification and maximizing the likelihood function. In particular, we compute the minimal primes of this ideal in the case of a binary latent class model with a binary or ternary hidden random variable.

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*Corresponding author.

Email address: serkan@sfsu.edu (Serkan Hoşten)

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1. Introduction

This paper is dedicated to the memory of Stephen and Joyce Fienberg.

Latent class models are popular models used in social sciences and machine learning. They were introduced in the 1950s by Paul Lazarsfeld [24] and were used to find groups in a population based on a hidden attribute (see also [25]). The model obtained its modern probabilistic formulation in the 1970s (e.g. [17]); we refer to [12] for a more detailed literature review. More recently, latent class models have also become widely used in machine learning, where they are called naive Bayes models. They are a popular method of text categorization, and are also used in other classification schemes [5, Section 8.2.2].

The latent class model is an instance of a model with incomplete data. Maximum likelihood estimation in such models may be challenging, and is typically done using the EM algorithm [9]. Stephen Fienberg in his discussion [11] of the paper introducing the EM algorithm shed some light on its potential problems—his comments are relevant to the latent class model. Referring to [18] Fienberg noted two main problems: (a) even for cases where the log-likelihood for the problem with complete data is concave, the log-likelihood for the incomplete problem need not be concave, and (b) the likelihood equations may not have a solution in the interior of the parameter space. He then wrote:

> In the first case multiple solutions of the likelihood equations can exist, not simply a ridge of solutions corresponding to a lack of identification of parameters, and in the second case the solutions of the likelihood equations occur on the boundary of the parameter space,[. . .].

The latent class model can be formulated as a graphical model with an unobserved variable defined by a star graph like in Figure 1. Given that the variable for the internal vertex was observed, the underlying model becomes a simple instance of an exponential family and, consequently, admits a concave log-likelihood function with a closed formula for the maximizer. However, the marginal likelihood will typically have many critical points, and the maxima may lie on the boundary of the model. In practice, to avoid the boundary problem, Bayesian methods need to be employed to push the solutions away from the boundary by using appropriate priors [14].

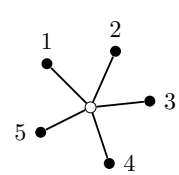

FIGURE 1: *The star graph model with* 5 *leaves. The internal vertex represents an unobserved random variable*

1.1. Outline of Results

Our aim is to study the boundary problem for the latent class model from the perspective of maximum likelihood estimation. We will use the link between latent class models and nonnegative tensor rank. For instance, the latent class model with three binary observed variables and one binary hidden variable is the model of normalized nonnegative $2 \times 2 \times 2$ tensors of nonnegative rank (rank_+) at most two. We will rely on recent work in algebraic statistics on the description of the (algebraic) boundary of tensors of nonnegative rank two [2]. Our Theorem 3.6 gives a complete characterization of the boundary strata of binary latent class models with a binary hidden variable.

The geometry of these models allows us to identify boundary strata for which the maximum likelihood problem is easy, such as certain codimension two strata; see Section 4.1. In Section 4.2, we showcase the use of Theorem 3.6 for the maximum likelihood estimation in the $2 \times 2 \times 2$ case of $\text{rank}_+ \leq 2$ by solving the problem exactly: we provide a formula for the maximizer of the likelihood function over the algebraic set defining each boundary strata. Together with recent work in [29], this is the first non-trivial example of the exact solution provided for a latent class model, which typically is fitted using the EM algorithm. The geometry used for this exact solution also provides insight into the maximum likelihood estimation in this model class, validating some of the concerns of Fienberg. We report the results of our simulations which show that the overwhelming majority of data has a maximum likelihood estimator on the boundary of the model (where some model parameters are zero). Indeed, under certain scenarios, even if the true underlying distribution lies in the interior of the model, the maximum likelihood estimator may be found on the boundary with high probability. We also examine briefly the model of $3 \times 3 \times 2$ tensors of nonnegative rank 3. Our simulations indicate that this model occupies a tiny portion (approximately .019%) of the probability simplex.

In Section 5, we study the algebraic description of the fixed points of the EM algorithm inspired by [22]. In particular, we compute the irreducible components of the EM fixed point ideal for the $2 \times 2 \times 2$ tensors of $\text{rank}_+ \leq 2$ and of $\text{rank}_+ \leq 3$. In the first case, we demonstrate that we can recover the formulas in Section 4.2 from certain components of the EM fixed point ideal via elimination. In the second case, the irreducible decomposition we compute validates the results in [29] on the boundary decomposition of this model.

2. Definitions and Background

If X is a random variable with values in $\{1, \ldots, k\}$, then its distribution is a point $(p_1, \ldots, p_k)$ in the *probability simplex*

$$\Delta_{k-1} \;=\; \{(x_1, \ldots, x_k) \in \mathbb{R}^k \,:\, x_1 + \ldots + x_k = 1,\;\; x_1, \ldots, x_k \geq 0\}.$$

The vector $X = (X_1, \ldots, X_n)$ is a *binary random vector* if $X_i \in \{1, 2\}$ for each $1 \leq i \leq n$. A *binary tensor* $P = (p_{i_1 \cdots i_n})$, where $i_j \in \{1, 2\}$, is a $2 \times 2 \times \cdots \times 2$ table of real numbers in $\mathbb{R}^{2 \times \cdots \times 2} = \mathbb{R}^{2^n}$. A tensor is *nonnegative* if it has only nonnegative entries. Every probability distribution for a binary vector $X = (X_1, \ldots, X_n)$ is a nonnegative binary

tensor in the probability simplex Δ_{2^n-1}:

$$p_{i_1 i_2 \cdots i_n} \;=\; \mathrm{Prob}(\{X_1 = i_1, X_2 = i_2, \ldots, X_n = i_n\}).$$

The *binary latent class model* $\mathcal{M}_{n,r}$ is a statistical model for a vector of n binary random variables $X = (X_1, \ldots, X_n)$. It contains all distributions such that $X_1, X_2, \ldots, X_n$ are independent given an unobserved random variable with $r \geq 1$ states. The model is parameterized by the distribution $\lambda = (\lambda_1, \lambda_2, \ldots, \lambda_r) \in \Delta_{r-1}$ of the unobserved variable and the conditional distributions of each X_i given the unobserved variable, which we write in form of a stochastic matrix

$$A^{(i)} \;=\; \begin{pmatrix} a_{11}^{(i)} & a_{12}^{(i)} \\ \vdots & \vdots \\ a_{r1}^{(i)} & a_{r2}^{(i)} \end{pmatrix}, \quad i = 1, \ldots, n,$$

where $a_{kl}^{(i)} \geq 0$ and $a_{j1}^{(i)} + a_{j2}^{(i)} = 1$ for each $j = 1, \ldots, r$. Letting C_n denote the n-dimensional cube Δ_1^n, then the parameter space of $\mathcal{M}_{n,r}$ is $\Theta := \Delta_{r-1} \times (C_n)^r$ with elements

$$\theta \;=\; (\lambda_1, \ldots, \lambda_r,\;\; a_{11}^{(1)}, a_{12}^{(1)}, \ldots, a_{r1}^{(1)}, a_{r2}^{(1)},\;\; \ldots,\;\; a_{11}^{(n)}, a_{12}^{(n)}, \ldots, a_{r1}^{(n)}, a_{r2}^{(n)}).$$

To be succinct, a choice of parameters θ is also denoted by $\theta = (\boldsymbol{\lambda}, A^{(1)}, A^{(2)}, \ldots, A^{(n)})$. The parameterization $\phi_{n,r} : \Theta \to \Delta_{2^n-1}$ of $\mathcal{M}_{n,r}$ is given by

$$\phi_{n,r} : \quad \theta \quad \mapsto \quad p_{j_1 j_2 \cdots j_n}(\theta) \;=\; \lambda_1 a_{1j_1}^{(1)} a_{1j_2}^{(2)} \cdots a_{1j_n}^{(n)} + \cdots + \lambda_r a_{rj_1}^{(1)} a_{rj_2}^{(2)} \cdots a_{rj_n}^{(n)}. \qquad (1)$$

This parameterization shows that the distributions in $\mathcal{M}_{n,r}$ admit a decomposition into r summands, which can be phrased in terms of tensor decompositions. A binary tensor P has *rank one* if it is an outer product of n vectors in $\mathbb{R}^2$; that is, there exist $u_1, \ldots, u_n \in \mathbb{R}^2$ such that $p_{i_1 i_2 \cdots i_n} = u_{1i_1} u_{2i_2} \cdots u_{ni_n}$. A tensor has *nonnegative rank (rank$_+$) at most* r if it can be written as a sum of r nonnegative tensors of rank one. Equivalently, a binary tensor with $\mathrm{rank}_+ \leq r$ is a point in the image of a map $\psi_{n,r} : (\mathbb{R}^2_{\geq 0})^{nr} \longrightarrow \mathbb{R}^{2^n}$ defined as

$$\psi_{n,r} : \;\; \prod_{i=1}^{n} \prod_{j=1}^{r} (u_{j1}^{(i)}, u_{j2}^{(i)}) \quad \mapsto \quad p_{i_1 i_2 \cdots i_n} \;=\; \sum_{j=1}^{r} u_{ji_1}^{(1)} u_{ji_2}^{(2)} \cdots u_{ji_n}^{(n)}.$$

For more on the connection between tensor rank, nonnegative tensor rank, and several of the latent class models under consideration here, see, for example, [1, 8] or for a connection to phylogenetic models [3]. Here we simply formulate the following result.

Proposition 2.1. *The set of binary tensors with rank$_+ \leq r$ is the cone over the binary latent class model $\mathcal{M}_{n,r}$.*

In this paper we focus primarily on models with two latent classes, $r = 2$, and write $\mathcal{M}_n := \mathcal{M}_{n,2}$ and $\phi_n := \phi_{n,2}$. This case in some ways is 'easy' since both the algebraic boundary (Proposition 3.1) and the singular set of the parameterization map (Proposition 3.3) are well understood. When considering questions of higher nonnegative rank, we have no such tools at our disposal. Binary tensors of $\text{rank}_+ \leq 2$ were studied in [2], where the following theorem gives a description of $\mathcal{M}_n$ as a semi-algebraic set.

Theorem 2.2. *[2, cf. Theorem 1.1] A binary tensor $P = (p_{i_1 i_2 \cdots i_n})$ has nonnegative rank at most two if and only if P has flattening rank at most two and P is supermodular.*

A matrix flattening of the binary tensor P is a $2^{|\Gamma|} \times 2^{n-|\Gamma|}$ matrix where $\Gamma \subset \{1, \ldots, n\}$ with $1 \leq |\Gamma| \leq n-1$. The flattening rank is the maximal rank of any of these matrices. This rank condition provides the equations for the semi-algebraic description since the rank of a matrix is at most two if and only if all 3-minors of that matrix vanish. Now, we briefly also explain the supermodularity. Let $\pi = (\pi_1, \ldots, \pi_n)$ be an n-tuple of permutations $\pi_j \in S_2$. We say P is π-supermodular if

$$p_{i_1 i_2 \cdots i_n}\, p_{j_1 j_2 \cdots j_n} \quad \leq \quad p_{k_1 k_2 \cdots k_n}\, p_{\ell_1 \ell_2 \cdots \ell_n} \tag{2}$$

holds when $\{i_s, j_s\} = \{k_s, \ell_s\}$ and $\pi_s(k_s) \leq \pi_s(\ell_s)$ for $s = 1, \ldots, n$. The tensor P is supermodular if it is π-supermodular for some π.

Corollary 2.3. *The semi-algebraic description of the binary latent class model is given by Theorem 2.2 together with the extra constraint that $\sum_{i_1,\ldots,i_n} p_{i_1 \cdots i_n} = 1$.*

We close this section with a result that simplifies some arguments regarding the boundary stratification of $\mathcal{M}_n$.

Lemma 2.4. *Let $\mathcal{M}_{n,r}$ be the latent class model for the random vector $X = (X_1, \ldots, X_n)$, and let $B \subset \{1, \ldots, n\}$ with $|B| = m$. Then the induced marginal model for $X_B = (X_i : i \in B)$ is $\mathcal{M}_{m,r}$. In particular, if P is a tensor in $\mathcal{M}_{n,r}$ given by parameters $(\lambda_1, \ldots, \lambda_r, A^{(1)}, \ldots, A^{(n)})$, then the corresponding marginal distribution P_B is given by parameters $\lambda_1, \ldots, \lambda_r$, and $A^{(i)}$ for $i \in B$.*

Proof. The marginal distribution P_B is obtained from $P = (p_{j_1 \cdots j_n})$ by summing over all indices j_k with $k \notin B$. When we compute the sum using the parameterization (1) the result follows because $a_{i1}^{(k)} + a_{i2}^{(k)} = 1$ for all $i = 1, \ldots, r$.

3. Boundary Stratification of $\mathcal{M}_n$

The semi-algebraic description of $\mathcal{M}_n$ can also be used to understand the topological boundary of this set. When $n = 1, 2$, $\mathcal{M}_n$ is well-understood: $\mathcal{M}_1 = \Delta_1$ and $\mathcal{M}_2 = \Delta_3$ respectively; see, e.g., [16, Corollary 2.2]. Thus we focus on the case of three or more observed variables, and assume that $n \geq 3$ throughout. We begin our analysis with the following proposition.

Proposition 3.1. *The dimension of the model $\mathcal{M}_n$ is $2n+1$. The boundary of this semi-algebraic set is defined by $2n$ irreducible components. Each component is the image of the set in the domain of ϕ_n given by $a_{1j}^{(i)} = 0$ for $i = 1, \ldots, n$ and $j = 1, 2$.*

Proof. The dimension of $\mathcal{M}_n$ is the number of independent parameters in the domain of ϕ_n. This follows because this model is generically identifiable, which is classically well known; see, e.g [26]. The statement about the boundary is Theorem 1.2 in [2], and the statement about each component is found in the proof of the same result.

Observe that these components are also defined by $a_{2j}^{(i)} = 0$, but one can interchange the rows of the matrices $A^{(i)}$ and the entries of λ, and get the same points on the boundary. This corresponds to 'label swapping' on the latent variable. Each component is the collection of tensors where one slice has rank one. By a *slice* of a tensor $P = (p_{i_1 \cdots i_n})$, we mean a subtensor obtained by fixing one index i_k. We note that for general tensors with nonnegative rank bigger than two, the boundary of the corresponding model $\mathcal{M}$ is not well understood. For instance, points on the boundary of the parameter space defined by setting one parameter equal to zero no longer map to the boundary of the model $\mathcal{M}$; see Example 5.2 in [2]. A recent development is [29] where the boundary of $\mathcal{M}_{3,3}$ has been described.

In this paper, we consider also lower dimensional pieces of the boundary of $\mathcal{M}_n$. Our motivation is to perform maximum likelihood estimation over such models efficiently. Proposition 3.1 implies that various intersections of the $2n$ irreducible codimension one components define lower dimensional boundary pieces. We call a set of boundary points of dimension k obtained as such an intersection a *k-dimensional stratum.* We will identify and describe the boundary strata that are relevant for maximum likelihood estimation. The relevant boundary strata are those which are not degenerate.

Definition 3.2. The degenerate part of Δ_{2^n-1} is the set of tensors $P = (p_{i_1 \cdots i_n})$ where for fixed $1 \leq j < k \leq n$ and a choice $i_j = s$ and $i_k = t$ with $s, t \in \{1, 2\}$ the entries $p_{i_1 \cdots s \cdots t \cdots i_n} = 0$ for all i_u, $u \neq j, k$.

Another way of detecting that a binary tensor P is degenerate is to look at the marginal table $P_{\{j,k\}}$. If any of the entries of this 2×2 table is zero for any j, k, then P is degenerate. For instance, if

$$P_{\{j,k\}} = \begin{pmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{pmatrix} = \begin{pmatrix} \alpha & 0 \\ \beta & \gamma \end{pmatrix}$$

with $\alpha, \beta, \gamma > 0$, then knowing that $X_j = 1$ implies that $X_k = 1$. By restricting to nondegenerate tensors, we avoid this kind of probabilistically degenerate situation. We could have formulated our main theorem only for the interior of the probability simplex, since from a mathematical point of view, extending it to some parts of the boundary seems like an incremental gain. From the statistical point of view, however, this gain is quite dramatic as it allows us to understand the maximum likelihood estimator even when data tables contain zeros (as long as two-way marginal tables have no zeros). This is especially important for validating the simulations in Section 4, when the sample sizes are relatively small.

3.1. Singular locus of the parametrization map

To state and prove our main result, we need an understanding of the singular locus of the parameterization map ϕ_n. Recall that a point of the domain Θ is a singular point of ϕ_n if the Jacobian of the map drops rank at this point. To describe this set, we look at various (overlapping) subsets of the parameter space. Specifically, let

$\Theta_{\lambda_1\lambda_2} \subseteq \Theta$ be the subset defined by $\lambda_1\lambda_2 = 0$;

$\Theta_{ij} \subseteq \Theta$ be the subset where $\text{rank}(A^{(k)}) = 1$ for all $k \neq i, j$ with $1 \leq i \neq j \leq n$; and

$\Theta_j \subseteq \Theta$ be the subset where $\text{rank}(A^{(k)}) = 1$ for all $k \neq j$.

Finally, we denote by Θ^1 the subset of Θ where $\text{rank}(A^{(k)}) = 1$ for all k. It is clear that $\Theta_{ij} = \Theta_{ji}$ and $\Theta^1 \subset \Theta_k \subset \Theta_{jk}$ for all $1 \leq j \neq k \leq n$.

The probabilistic interpretation of these special loci is simple. The set $\Theta_{\lambda_1\lambda_2}$ corresponds to the parameters for which the latent variable is degenerate taking always the value 0, or always the value 1. The set Θ_{ij} corresponds to the special situation where all variables X_k for $k \neq i, j$ are probabilistically independent of the latent variable. That is, only two observable variables in the system carry some information about the latent one. In the case of Θ_j, only X_j is allowed to nontrivially depend on the latent variable, and Θ^1 corresponds to points where all observed random variables are independent of the latent one. Note that the points in the sets $\Theta_{\lambda_1\lambda_2}$, Θ_j, and Θ^1 correspond to the situation where all observed variables are independent of each other.

Remark: For those familiar with tensor decompositions, these subsets of parameters have simple descriptions in terms of the ranks of the matrices $A^{(i)}$. Suppose that $\theta = (\boldsymbol{\lambda}, A^{(1)}, \ldots, A^{(n)})$, then the *m-rank* of θ is the n-tuple $(\text{rank}(A^{(1)}), \ldots, \text{rank}(A^{(n)}))$. In this setting, we see that, for example, Θ_{12} corresponds to parameters with m-rank $(r_1, r_2, 1, 1, \ldots, 1)$ with $r_1, r_2 \leq 2$. The subset Θ_1 corresponds to parameters with m-rank $(r_1, 1, 1, \ldots, 1)$, and Θ^1 to those parameters with m-rank $(1, 1, \ldots, 1)$. Indeed, this perspective makes it quite easy to determine both the singular locus of ϕ_n and the tensor rank of the images of these parameter sets.

Proposition 3.3. *The singular locus of the parametrization map ϕ_n is equal to*

$$\Theta_{\lambda_1\lambda_2} \cup \bigcup_{1 \leq i \neq j \leq n} \Theta_{ij}.$$

This result is not new, cf. [27, Corollary 7.17] and could also be inferred from Theorems 13 and 14 in [15]. We provide an alternative proof that is based on ideas from [1] and [8].

Proof. [Proof of Proposition 3.3] It is clear that the sets $\Theta_{\lambda_1\lambda_2}$ and Θ^1 map under ϕ_n to distributions in $\mathcal{M}_n$ of nonnegative rank 1, and thus that the Jacobian drops rank at these points. A simple computation shows that ϕ_n maps points in Θ_k to tensors of

$\text{rank}_+ = 1$, and the Jacobian is rank deficient at these parameter points too. Consider now those parameters θ with (up to permutation) m-rank $(2, 2, 1, \ldots, 1)$ and, without loss of generality, $\theta \notin \Theta_{\lambda_1,\lambda_2}$. Let $P_\theta = \phi_n(\theta)$. We quickly show that P_θ has nonnegative rank 2, and that θ is a singular point of the parameterization. Since $A^{(3)}, \ldots, A^{(n)}$ are singular matrices, let $\mathbf{v}$ be the tensor product of their top rows. Stated in more statistical language, $\mathbf{v}$ is the (vectorized) joint distribution of the independent binary variables $X_3, \ldots, X_n$. Using $A^{(1)}, A^{(2)}$ for the matrix parameters of rank 2, then the joint distribution P_θ is $P_\theta = (A^{(1)})^T \operatorname{diag}([\lambda_1, \lambda_2])\, A^{(2)} \otimes \mathbf{v}$. Since $(A^{(1)})^T \operatorname{diag}([\lambda_1, \lambda_2])\, A^{(2)}$ is a rank 2 matrix, P_θ is a rank 2 tensor. However, the fiber of P_θ is positive dimensional. This follows because the matrix factorization $(A^{(1)})^T \operatorname{diag}([\lambda_1, \lambda_2])\, A^{(2)}$ above is not unique. If Σ is taken to be any matrix sufficiently close to the identity and with column sums equal to 1, then $\tilde{A}^{(1)} = \Sigma^T A^{(1)}$ is Markov, $\tilde{\boldsymbol{\lambda}} = \Sigma^{-1} \operatorname{diag}([\lambda_1, \lambda_2]) A^{(2)} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ has positive entries, $\tilde{A}^{(2)} = \operatorname{diag}(\tilde{\boldsymbol{\lambda}})^{-1} \Sigma^{-1} \operatorname{diag}([\lambda_1, \lambda_2]) A^{(2)}$ is Markov, and $\phi_n(\tilde{\boldsymbol{\lambda}}, \tilde{A}^{(1)}, \tilde{A}^{(2)}, A^{(3)}, \ldots A^{(n)})$ also equals P_θ. It follows that θ is a singular point of the parameterization ϕ_n.

Finally, consider parameters θ of m-rank $(2, 2, 2, r_4, \ldots, r_n)$ up to permutation, $\theta \notin \Theta_{\lambda_1\lambda_2}$. Then by Kruskal's Theorem [20, 21] together with techniques developed in [1] for proving parameter identifiability, θ is identifiable and the fiber of P_θ is of size 2. This means that θ is not a singular point of ϕ_n.

We now state and prove two lemmas used repeatedly in the proof of Theorem 3.6.

Lemma 3.4. *$\phi_n(\Theta_{ij})$ is an $(n+1)$-dimensional subset of Δ_{2^n-1} isomorphic to $\Delta_3 \times (\Delta_1)^{n-2}$.*

Proof. A 2×2 stochastic matrix has rank one if and only if both of its rows are equal. Therefore, points in the image of Θ_{ij} are of the form

$$p_{k_1 \cdots k_n} \;=\; (\lambda_1 a^{(i)}_{1k_i} a^{(j)}_{1k_j} + \lambda_2 a^{(i)}_{2k_i} a^{(j)}_{2k_j}) \prod_{l \neq i,j} a^{(l)}_{1k_l}.$$

It is clear that $\phi_n(\Theta_{ij})$ is a subset of Δ_{2^n-1} isomorphic to $\mathcal{M}_2 \times (\Delta_1)^{n-2}$. The equality follows because $\mathcal{M}_2 = \Delta_3$.

Lemma 3.5. *The parametrization ϕ_n maps $\Theta_{ij} \cap \{a^{(k)}_{st} = 0\}$ for $k \neq i, j$ and $s, t \in \{1, 2\}$ to the degenerate part of the boundary of Δ_{2^n-1}.*

Proof. Consider the case $a^{(k)}_{11} = 0$. Then $a^{(k)}_{12} = 1$, and since $A^{(k)}$ has rank one we conclude that $a^{(k)}_{21} = 0$ and $a^{(k)}_{22} = 1$. This means that the first slice of the image tensor along dimension k is identically zero. Similar reasoning applies for all $a^{(k)}_{st} = 0$.

Below we consider the intersection of various subsets of the boundary of Θ with pieces of the singular locus. Motivated by the last lemma, we denote $\Theta_{ij} \cap \operatorname{int}(\Theta)$ by Θ°_{ij}. We also let $\Theta^\circ_j = \Theta_j \cap \operatorname{int}(\Theta)$.

3.2. Main Theorem

We now state our main theorem.

Theorem 3.6. *For $n \leq k \leq 2n+1$, the k-dimensional strata of the nondegenerate part of $\mathcal{M}_n$ are in bijection with the $k-(n+1)$-dimensional faces of the cube C_n, except for $k = 2n-1$ when n additional strata are present, and for $k = n+1$ when $\binom{n}{2}$ additional strata are present. More precisely, the stratification of $\mathcal{M}_n$ has five types of strata:*

1. *The interior of $\mathcal{M}_n$. This strata has dimension $2n+1$ and each point is the image under ϕ_n of a nonsingular point in the interior of Θ.*

2. *Non-exceptional strata of dimension $n+1 \leq k \leq 2n$. Except for $k = 2n-1$, each k-dimensional stratum is the image of points in*

$$\left(\bigcap_{s_i : i \in I} \{a^{(i)}_{1s_i} = 0\} \right) \bigcup \left(\bigcap_{s_i : i \in I} \{a^{(i)}_{2s_i} = 0\} \right),$$

   where $|I| = 2n+1-k$. For $k = 2n-1$, a stratum corresponding to a codimension two face of C_n is the image of points in

$$\{a^{(i)}_{1s} = 0\} \cap \{a^{(j)}_{1t} = 0\} \bigcup \{a^{(i)}_{2s} = 0\} \cap \{a^{(j)}_{2t} = 0\} \bigcup \Theta^{\circ}_{ij},$$

   for $1 \leq i < j \leq n$ and $s, t = 1, 2$.

3. *Exceptional strata of dimension $2n-1$. These are n additional strata given as the image of points in*

$$\{a^{(i)}_{11} = 0\} \cap \{a^{(i)}_{22} = 0\} \bigcup \{a^{(i)}_{12} = 0\} \cap \{a^{(i)}_{21} = 0\},$$

   for $i = 1, \ldots, n$.

4. *Exceptional strata of dimension $n+1$. These are $\binom{n}{2}$ additional strata given as the image of points in Θ°_{ij} for $1 \leq i < j \leq n$.*

5. *A single n-dimensional stratum corresponding to the empty face of C_n given by the image of points in $\Theta_{\lambda_1 \lambda_2}$.*

Corollary 3.7. *Let $n \leq k \leq 2n+1$ with $k = 2n+1-\ell$. Then the number of nondegenerate k-dimensional strata of $\mathcal{M}_n$ is*

$$\begin{cases} \binom{n}{\ell} 2^{\ell} & \ell \neq 2, n, n+1 \\ \binom{n}{2} 4 + n & \ell = 2 \\ 2^n + \binom{n}{2} & \ell = n \\ 1 & \ell = n+1. \end{cases}$$

We prove Theorem 3.6 at the end of this section, after making a few comments about the stratification. As a general rule, the set of probability distributions contained in a single stratum does not allow a clean and simple interpretation. In a few cases, however, we *do* observe nice patterns, and we describe these below.

(a) *Codimension one strata.* The $2n$ codimension one strata have a simple recursive description. For example, if $a_{11}^{(1)} = 0$ then $a_{12}^{(1)} = 1$, and the slice $(p_{1j_2\cdots j_n})$ of the tensor P is a binary tensor of rank one. This corresponds to the context specific independence model where $X_2, \ldots, X_n$ are independent conditionally on $\{X_1 = 1\}$. It is described in the probability simplex $\Delta_{2^{n-1}-1}$ by the binomial equations

$$p_{1i_2\cdots i_n}p_{1j_2\cdots j_n} - p_{1k_2\cdots k_n}p_{1l_2\cdots l_n} \;=\; 0 \quad \text{for } \{i_s, j_s\} = \{k_s, l_s\} \text{ and } s = 2, \ldots, n. \tag{3}$$

The other slice $(p_{2j_2\cdots j_n})$, after normalization, is a tensor from the model $\mathcal{M}_{n-1}$. Hence, knowing the description of $\mathcal{M}_{n-1}$ helps describe the codimension one strata of $\mathcal{M}_n$.

(b) *The exceptional codimension two strata (type (3)).* If $A^{(1)}$ is the identity matrix, then the parameterization in (1) specializes to

$$p_{1j_2\cdots j_n} = \lambda_1 a_{1j_2}^{(2)} \cdots a_{1j_n}^{(n)}, \qquad p_{2j_2\cdots j_n} = \lambda_2 a_{2j_2}^{(2)} \cdots a_{2j_n}^{(n)}.$$

Since $A^{(2)}, \ldots, A^{(n)}$ are arbitrary stochastic matrices, the first stratum of type (3) corresponds to the model where $X_2, \ldots, X_n$ are independent conditionally on X_1. This is a graphical model given by the graph in Figure 2. This model is fully described in the probability simplex Δ_{2^n-1} by the binomial equations

$$p_{ii_2\cdots i_n}p_{ij_2\cdots j_n} - p_{ik_2\cdots k_n}p_{il_2\cdots l_n} \;=\; 0 \quad \text{for } i = 1, 2,\ \{i_s, j_s\} = \{k_s, l_s\} \text{ and } s = 2, \ldots, n$$

with no additional inequalities. The analysis is analogous for the $n-1$ remaining strata given by one of $A^{(2)}, \ldots, A^{(n)}$ being the identity matrix.

(c) *The n-dimensional stratum (type(5)).* This unique stratum is given by all rank one tensors in Δ_{2^n-1}. This stratum is defined by the equations

$$p_{i_1i_2\cdots i_n}p_{j_1j_2\cdots j_n} - p_{k_1k_2\cdots k_n}p_{l_1l_2\cdots l_n} \;=\; 0 \quad \text{if } \{i_s, j_s\} = \{k_s, l_s\} \text{ for } s = 1, \ldots, n$$

and it corresponds to the full independence model.

The strata of $\mathcal{M}_n$ form a partially ordered set where for two strata S, S' we have $S \preceq S'$ if the closure of S is contained in the closure of S'. Such a partially ordered set structure becomes important in Section 4 to provide further insights into the geometry of the maximum likelihood estimation. Suppose that p^* is a maximizer of a function f over the (Zariski) closure of a set S'. If S is another set such that $S \preceq S'$ then the value of f in S is bounded above by $f(p^*)$. In particular, if p^* lies in S' then to maximize f over $\mathcal{M}_n$ there is no need to check strata S such that $S \preceq S'$.

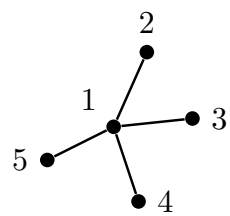

FIGURE 2: *The graph representing the strata given by* $a_{12}^{(1)} = a_{21}^{(1)} = 0$.

The interior of $\mathcal{M}_n$ is the unique maximal element, and the unique strata of type (5) is the unique minimal element. For example, for $\mathcal{M}_3$ there are six dimension 6 strata, which we label by $\{1, 2, 3, 4, 5, 6\}$ corresponding to equations

$$\begin{array}{llll} (1) & p_{111}p_{122} = p_{112}p_{121} & (2) & p_{211}p_{222} = p_{212}p_{221} \\ (3) & p_{111}p_{212} = p_{112}p_{211} & (4) & p_{121}p_{222} = p_{122}p_{221} \\ (5) & p_{111}p_{221} = p_{121}p_{211} & (6) & p_{112}p_{222} = p_{122}p_{212} \end{array}$$

respectively. These six equations are naturally grouped in pairs as indicated by the three rows above. Each of these three pairs defines one of the three special strata of type (3). In general, each special stratum of this kind is obtained as the intersection of codimension one strata which correspond to "opposite" facets of C_n. For $\mathcal{M}_3$, each special stratum of type (4) is defined by four equations found in two rows of the six equations above. If one ignores these special strata, the poset is isomorphic to the face poset of the cube C_n. The Hasse diagram of the poset for $\mathcal{M}_3$ is given in Figure 3.

We now turn to the proof of Theorem 3.6. The result will follow from a sequence of lemmas. By Proposition 3.1 there are exactly $2n$ strata of codimension one, each consisting of tensors where in one slice along a given dimension the subtensor has rank at most one. In other words, each stratum is described by a collection of equations of the form (3) together with the inequalities forcing supermodularity. We denote these strata by Γ_{is} where $i = 1, \ldots, n$ and $s = 1, 2$.

We first formulate a lemma that shows that boundary points are mapped to boundary points under the marginalization $P \mapsto P_B$ (c.f. Lemma 2.4).

Lemma 3.8. *Suppose that $n \geq 4$ and let $B \subset \{1, \ldots, n\}$ with $|B| = m \geq 3$. For $i \in B$, if a point P in $\mathcal{M}_n$ lies on Γ_{is}, then P_B lies in the corresponding stratum Γ_{is} of the marginal model $\mathcal{M}_m$.*

Proof. If P is the image of $(\lambda_1, \lambda_2, A^{(k)} : k = 1, \ldots, n)$, by Lemma 2.4, P_B is the image of $(\lambda_1, \lambda_2, A^{(k)} : k \in B)$. Hence if the slice s in dimension i of P has rank one, so will the slice s in dimension i of P_B.

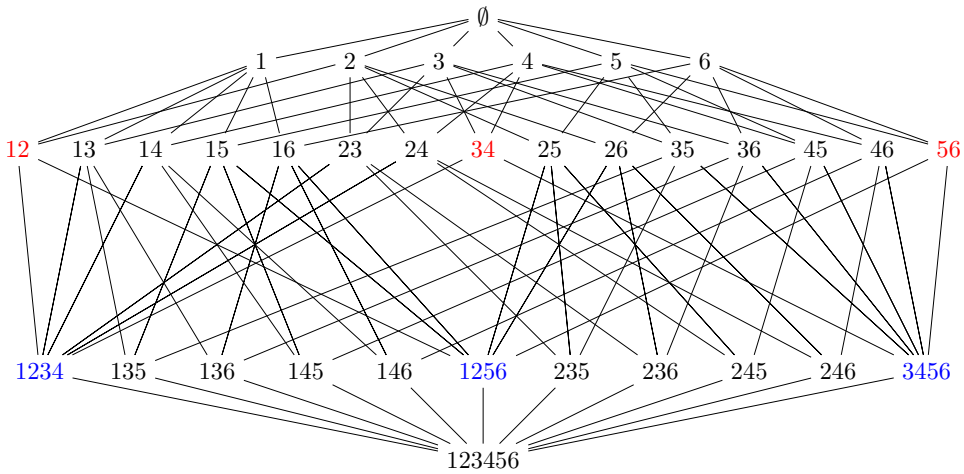

FIGURE 3: *The boundary stratification poset of $\mathcal{M}_3$. The red and blue nodes correspond to strata of type (3) and of type (4), respectively.*

Proposition 3.9. *The preimage of the codimension one stratum Γ_{is} under ϕ_n is*

$$\phi_n^{-1}(\Gamma_{is}) \;=\; \{a_{1s}^{(i)} = 0\} \cup \{a_{2s}^{(i)} = 0\} \cup \Theta_{\lambda_1\lambda_2} \cup \bigcup_{k\neq i} \Theta_{ik}^{\circ}.$$

Proof. We first show that

$$\{a_{1s}^{(i)} = 0\} \cup \{a_{2s}^{(i)} = 0\} \cup \Theta_{\lambda_1\lambda_2} \cup \bigcup_{k\neq i} \Theta_{ik}^{\circ} \quad \subset \quad \phi_n^{-1}(\Gamma_{is}).$$

Clearly $\{a_{1s}^{(i)} = 0\} \cup \{a_{2s}^{(i)} = 0\} \cup \Theta_{\lambda_1\lambda_2}$ lies in the preimage. To show that the preimage contains also Θ_{ik}° for each $k \neq i$, note that the image of a point in Θ_{ik}° is given by

$$p_{j_1\cdots j_i\cdots j_k\cdots j_n} = (\lambda_1 a_{1j_i}^{(i)} a_{1j_k}^{(k)} + \lambda_2 a_{2j_i}^{(i)} a_{2j_k}^{(k)}) \prod_{l\neq i,k} a_{1j_l}^{(l)}.$$

The points on Γ_{is} must satisfy $p_{i_1\cdots s\cdots i_n} p_{j_1\cdots s\cdots j_n} = p_{\nu_1\cdots s\cdots \nu_n} p_{\mu_1\cdots s\cdots \mu_n}$ for $\{i_t, j_t\} = \{\nu_t, \mu_t\}$ where $1 \leq t \neq i \leq n$. The above point satisfies such equations since

$$(\lambda_1 a_{1s}^{(i)} a_{1i_k}^{(k)} + \lambda_2 a_{2s}^{(i)} a_{2i_k}^{(k)})(\lambda_1 a_{1s}^{(i)} a_{1j_k}^{(k)} + \lambda_2 a_{2s}^{(i)} a_{2j_k}^{(k)}) =$$

$$(\lambda_1 a_{1s}^{(i)} a_{1\nu_k}^{(k)} + \lambda_2 a_{2s}^{(i)} a_{2\nu_k}^{(k)})(\lambda_1 a_{1s}^{(i)} a_{1\mu_k}^{(k)} + \lambda_2 a_{2s}^{(i)} a_{2\mu_k}^{(k)}).$$

Next we show that no other points lie in the preimage. To this end, from now on suppose that $a_{1s}^{(i)} \neq 0$, $a_{2s}^{(i)} \neq 0$, $\lambda_1 \cdot \lambda_2 \neq 0$ and the parameters are not in $\bigcup_{k\neq i} \Theta_{ik}^{\circ}$. Hence we

can assume that $P \in \Gamma_{is}$ is given by a parameter vector such that for some $j, k \neq i$ the matrices $A^{(j)}, A^{(k)}$ have rank 2. Consider the marginal distribution over $\{i, j, k\}$ and denote its coordinates by $q_{u_i u_j u_k}$, $u_i, u_j, u_k \in \{1, 2\}$. By Lemma 3.8, it is a point in $\mathcal{M}_3$ parameterized by $(\lambda_1, \lambda_2, A^{(i)}, A^{(j)}, A^{(k)})$, and it satisfies $q_{s11}q_{s22} = q_{s12}q_{s21}$. A quick computation shows that this is equivalent to

$$\lambda_1 \lambda_2 a_{1s}^{(i)} a_{2s}^{(i)} \det(A^{(j)}) \det(A^{(k)}) \ = \ 0. \tag{4}$$

However, by our assumption, this is impossible.

Our strategy to prove Theorem 3.6 is to intersect preimages of codimension one strata Γ_{is}. By Proposition 3.9, this means we must consider intersections of subsets of the boundary of the parameter space Θ and of various subsets of the singular locus of ϕ_n in the interior of Θ. When doing this, we disregard two types of intersections. The first type consists of subsets of the parameter space whose points map to the degenerate part of Δ_{2^n-1}. Since we are interested in nondegenerate points in the intersections of Γ_{is}, these kinds of subsets are irrelevant. The second type consists of subsets of the parameter space whose points map to tensors of rank one. The next proposition justifies the irrelevance of these subsets.

Proposition 3.10. *The intersection of all Γ_{is} for $i = 1, \ldots, n$ and $s = 1, 2$ contains all tensors of rank one.*

Proof. Every tensor in Δ_{2^n-1} of rank one is the image of a parameter vector in Θ where $\lambda_1 = 0$. Such a parameter vector is in $\Theta_{\lambda_1\lambda_2}$. By Proposition 3.9, the image of $\Theta_{\lambda_1\lambda_2}$ under the parametrization map is contained in every Γ_{is}.

In Corollary 3.19 we prove that the intersection of all nondegenerate points in Γ_{is} for $i = 1, \ldots, n$, $s = 1, 2$ is *equal* to the set of nondegenerate tensors of rank one. This intersection gives us the unique n-dimensional stratum (type (5)). Hence, when intersecting preimages of Γ_{is} we ignore parameters mapping to tensors of rank one since their images are in every possible intersection. In summary, when we refer to intersections of $\phi_n^{-1}(\Gamma_{is})$ we consider only the *relevant* part, meaning only those points that do not map to degenerate or rank one tensors. For instance, by Proposition 3.9 the relevant part of $\phi_n^{-1}(\Gamma_{is})$ consists of $\{a_{1s}^{(i)} = 0\} \cup \{a_{2s}^{(i)} = 0\} \cup \bigcup_{k \neq i} \Theta_{ik}^{\circ}$.

Lemma 3.11. *The relevant part of $\phi_n^{-1}(\Gamma_{is}) \cap \phi_n^{-1}(\Gamma_{jt})$ where $i \neq j$ is*

$$\{a_{1s}^{(i)} = 0\} \cap \{a_{1t}^{(j)} = 0\} \bigcup \{a_{2s}^{(i)} = 0\} \cap \{a_{2t}^{(j)} = 0\} \bigcup \Theta_{ij}^{\circ}.$$

Proof. The points in the set $\{a_{1s}^{(i)} = 0\} \cap \{a_{2t}^{(j)} = 0\}$ map to degenerate tensors since in the marginalization of the image tensor $P_{\{i,j\}}(X_i = s, X_j = t) = 0$. A similar argument shows that $\{a_{2s}^{(i)} = 0\} \cap \{a_{1t}^{(j)} = 0\}$ is irrelevant. So we just need to compute the intersection of $\cup_{k \neq i} \Theta_{ik}^{\circ}$ and $\cup_{\bar{k} \neq j} \Theta_{j\bar{k}}^{\circ}$. When $k = j$ and $\bar{k} = i$, we get Θ_{ij}°. Also, $\Theta_{ij}^{\circ} \cap \Theta_{j\bar{k}} = \Theta_j^{\circ}$ when $\bar{k} \neq i$, and $\Theta_{ik}^{\circ} \cap \Theta_{ji} = \Theta_i^{\circ}$ when $k \neq j$. Both are irrelevant. For the case $k \neq j$ and $\bar{k} \neq i$, we either get Θ^1 if $k \neq \bar{k}$, or Θ_k° if $k = \bar{k}$. Again both cases give irrelevant subsets.

Corollary 3.12. *The nondegenerate intersection of* Γ_{is} *with* Γ_{jt} *where* $i \neq j$ *is a stratum of dimension* $2n-1$*. There are* $\binom{n}{2}4$ *such strata.*

Proof. The parametrization map ϕ_n is generically smooth on $\bigcup_{u=1,2}\{a_{us}^{(i)}=0\}\cap\{a_{ut}^{(j)}=0\}$, and a simple parameter count shows that this set has dimension equal to $2n-1$. Together with Lemma 3.4 this implies the result. For each $1 \leq i < j \leq n$ and each choice of $s,t \in \{1,2\}$ we get such a stratum. Hence, there are $\binom{n}{2}4$ of them.

Lemma 3.13. *The relevant part of* $\phi_n^{-1}(\Gamma_{i1}) \cap \phi_n^{-1}(\Gamma_{i2})$ *is*

$$\{a_{11}^{(i)}=0\}\cap\{a_{22}^{(i)}=0\}\bigcup\{a_{12}^{(i)}=0\}\cap\{a_{21}^{(i)}=0\}\bigcup\cup_{k\neq i}\Theta_{ik}^{\circ}.$$

Proof. The intersections $\{a_{11}^{(i)}=0\}\cap\{a_{12}^{(i)}=0\}$ and $\{a_{21}^{(i)}=0\}\cap\{a_{22}^{(i)}=0\}$ are empty in the parameter space Θ.

Corollary 3.14. *The nondegenerate intersection* $\Gamma_{i1}\cap\Gamma_{i2}$ *is a stratum of dimension* $2n-1$*. There are* n *such exceptional strata.*

Proof. The parametrization map ϕ_n is generically smooth on $\{a_{11}^{(i)}=0\}\cap\{a_{22}^{(i)}=0\}$, and on $\{a_{12}^{(i)}=0\}\cap\{a_{21}^{(i)}=0\}$, and the dimension of this set is $2n-1$. Together with Lemma 3.4 this gives the first statement. The count is obvious.

Lemma 3.15. *The relevant part of* $\phi_n^{-1}(\Gamma_{is})\cap\phi_n^{-1}(\Gamma_{jt})\cap\phi_n^{-1}(\Gamma_{kv})$ *where* i,j,k *are distinct is*

$$\bigcup_{u=1,2}\{a_{us}^{(i)}=0\}\cap\{a_{ut}^{(j)}=0\}\cap\{a_{uv}^{(k)}=0\}.$$

Proof. We proceed as in the proof Lemma 3.11. After discarding irrelevant subsets such as $\{a_{1s}^{(i)}=0\}\cap\{a_{1t}^{(j)}=0\}\cap\{a_{2v}^{(k)}=0\}$ (since they map to degenerate tensors) we also see that the desired intersection contains $\Theta_{ij}^{\circ}\cap\Theta_{ik}^{\circ}\cap\Theta_{jk}^{\circ}=\Theta^1$. This is also irrelevant.

This result immediately generalizes to higher-order intersections.

Corollary 3.16. *Let* $I \subset \{1,\ldots,n\}$ *where* $|I|=\ell \geq 3$*. Then for each choice of* $s_i \in \{1,2\}$ *for* $i \in I$ *the nondegenerate intersection* $\bigcap_{i\in I}\Gamma_{is_i}$ *is a stratum of dimension* $2n+1-\ell$*. There are* $\binom{n}{\ell}2^{\ell}$ *such strata.*

Proof. Lemma 3.15 implies that the relevant part of $\bigcap_{i\in I}\phi_n^{-1}(\Gamma_{is_i})$ is

$$\bigcup_{u=1,2}\left(\bigcap_{s_i:i\in I}\{a_{us_i}^{(i)}=0\}\right).$$

Each piece of this union has dimension $2n+1-\ell$, and since ϕ_n is generically smooth on these sets the intersection $\bigcap_{i\in I}\Gamma_{is_i}$ is a stratum of the same dimension. It is easy to count such strata.

Lemma 3.17. *The relevant part of* $\phi_n^{-1}(\Gamma_{i1}) \cap \phi_n^{-1}(\Gamma_{i2}) \cap \phi_n^{-1}(\Gamma_{j1})$ *is* Θ_{ij}°*. Moreover, this is equal to the relevant part of* $\phi_n^{-1}(\Gamma_{i1}) \cap \phi_n^{-1}(\Gamma_{i2}) \cap \phi_n^{-1}(\Gamma_{j1}) \cap \phi_n^{-1}(\Gamma_{j2})$*.*

Proof. We have computed $\phi_n^{-1}(\Gamma_{i1}) \cap \phi_n^{-1}(\Gamma_{i2})$ in Lemma 3.13. Together with Proposition 3.9 we conclude that we need to describe the intersection of

$$\{a_{11}^{(i)} = 0\} \cap \{a_{22}^{(i)} = 0\} \bigcup \{a_{12}^{(i)} = 0\} \cap \{a_{21}^{(i)} = 0\} \bigcup \cup_{k \neq i} \Theta_{ik}^\circ$$

with

$$\{a_{11}^{(j)} = 0\} \cup \{a_{21}^{(j)} = 0\} \bigcup \cup_{k \neq j} \Theta_{jk}^\circ.$$

Up to symmetry, we get the following intersections: (i) $\{a_{12}^{(i)} = 0, a_{21}^{(i)} = 0, a_{11}^{(j)} = 0\}$, (ii) Θ_{ij}°. It is therefore enough to show that the first set is irrelevant. Let P be a tensor that is in the image of a point in the set (i). Then in the marginal distribution $P_{\{i,j\}}$ we have $P_{\{i,j\}}(X_i = 1, X_j = 1) = 0$. Hence P is degenerate. Finally, when we intersect further with $\phi_n^{-1}(\Gamma_{j2}) = \{a_{12}^{(j)} = 0\} \cup \{a_{22}^{(j)} = 0\} \cup \bigcup_{k \neq j} \Theta_{jk}^\circ$, still the only thing that survives as relevant is Θ_{ij}°.

Corollary 3.18. *For* $i \neq j$*, the nondegenerate points in the intersection* $\Gamma_{i1} \cap \Gamma_{i2} \cap \Gamma_{j1} \cap \Gamma_{j2}$ *is a stratum of dimension* $n+1$*. There are* $\binom{n}{2}$ *such strata.*

Proof. The nondegenerate intersection given in the statement is the image of Θ_{ij}° by Lemma 3.17. This intersection is not contained in any other Γ_{k1} or Γ_{k2} for $k \neq i, j$ since by Proposition 3.9 everything in $\Theta_{ij}^\circ \cap \phi_n^{-1}(\Gamma_{k1})$ maps to tensors of rank one. Hence, indeed $\Gamma_{i1} \cap \Gamma_{i2} \cap \Gamma_{j1} \cap \Gamma_{j2}$ defines a stratum. Lemma 3.4 implies that the dimension of this stratum is $n+1$. Clearly, there are $\binom{n}{2}$ such strata.

Corollary 3.19. *The intersection of all nondegenerate points in* Γ_{is} *for* $i = 1, \ldots, n$*,* $s = 1, 2$ *is the unique stratum of dimension* n *consisting of all nondegenerate tensors of rank one.*

Proof. From Proposition 3.10 the intersection contains the set of tensors of rank one. Corollary 3.18 implies that $\bigcap_{s=1,2} (\Gamma_{is} \cap \Gamma_{js} \cap \Gamma_{ks})$ is contained in the set of tensors of rank one establishing that the intersection of all codimension one strata is a stratum. The dimension of the set of rank one tensors is n.

Finally, we prove the main theorem.

Proof of Theorem 3.6: Proposition 3.1 implies that the interior of $\mathcal{M}_n$ has dimension $2n+1$. The above results imply that any parameter vector with $a_{1s}^{(i)} = 0$ or $a_{2s}^{(i)} = 0$ for $s = 1, 2$ maps to the algebraic boundary of $\mathcal{M}_n$. Similarly, any parameter vector in Θ_{ij}° for $1 \leq i \neq j \leq n$ as well as a parameter vector in $\Theta_{\lambda_1 \lambda_2}$ is mapped to the boundary of $\mathcal{M}_n$. The remaining parameter vectors must map to the interior of $\mathcal{M}_n$, and these points are nonsingular parameter vectors that are in the interior of Θ. We will associate the interior of $\mathcal{M}_n$ with the interior of the n-dimensional cube C_n.

Also by Proposition 3.1, Γ_{is} for $i = 1, \ldots, n$ and $s = 1, 2$ are precisely the $2n$ boundary strata of dimension $2n$. They are in bijection with the $2n$ facets of C_n. By Proposition 3.9, the preimage of each Γ_{is} is $\{a^{(i)}_{1s} = 0\} \cup \{a^{(i)}_{2s} = 0\} \cup \Theta_{\lambda_1\lambda_2} \cup \bigcup_{k\neq i} \Theta^{\circ}_{ik}$. Lemma 3.11 proves that $\Gamma_{is} \cap \Gamma_{jt}$ for $i \neq j$ is the image of points in $\{a^{(i)}_{1s} = 0\} \cap \{a^{(j)}_{1t} = 0\} \bigcup \{a^{(i)}_{2s} = 0\} \cap \{a^{(j)}_{2t} = 0\} \bigcup \Theta^{\circ}_{ij}$. By Corollary 3.12 this is the non-exceptional strata of dimension $k = 2n - 1$ and these strata correspond to $(n - 2)$-dimensional faces of C_n which are obtained as intersections of nonparallel facets of the cube (i.e. $i \neq j$). Lemma 3.15 and Corollary 3.16 take care of the non-exceptional strata of dimension $n < k < 2n - 1$ as the image of $\bigcup_{u=1,2} \left(\bigcap_{s_i : i\in I} \{a^{(i)}_{us_i} = 0\} \right)$. This image is the intersection of $\bigcap_{i\in I} \Gamma_{is_i}$ where $|I| = 2n + 1 - k$. They correspond to faces of C_n of dimension $k - n - 1$. This describes all nondegenerate strata of types (1) and (2) in the statement of the theorem.

The exceptional strata of codimension two ($k = 2n-1$), that is of type (3), is described by Lemma 3.13 and Corollary 3.14, combined with the proof of Lemma 4.5 in [2]. The statement about the exceptional strata (type (4)) of dimension $k = n + 1$ follows from Lemma 3.17 and Corollary 3.18. And finally, the proof of Lemma 3.17 and Corollary 3.19 provide the description of the unique n-dimensional stratum given in type (5). □

4. Maximum likelihood estimation over $\mathcal{M}_n$

In this section we present how our understanding of the boundary of $\mathcal{M}_n$ provides a partial understanding of the maximum likelihood estimation over this model class. For $\mathcal{M}_3$, maximum likelihood estimators are computed exactly.

Suppose an independent sample of size $N > 1$ was observed from a binary distribution. We report the data in a tensor of counts $U = (u_{i_1\cdots i_n})$ where $u_{i_1\cdots i_n}$ is the number of times the event $\{X_1 = i_1, \ldots, X_n = i_n\}$ was observed. The sum of all elements in U is equal to N. The log-likelihood function $\ell : \Theta \longrightarrow \mathbb{R}$ is

$$\ell(\theta) \;=\; \sum_{i_1,\ldots,i_n=1}^{2} u_{i_1\cdots i_n} \log(p_{i_1\cdots i_n}(\theta)), \tag{5}$$

where $p_{i_1\cdots i_n}(\theta)$ is as in (1). In this section we are interested in maximizing the log-likelihood function over $\mathcal{M}_n$ to compute a maximum likelihood estimate (MLE) for the data U. We remark that $\ell(\theta)$ is a strictly concave function on the entire Δ_{2^n-1}, and if its unique maximizer over the entire probability simplex is not in $\mathcal{M}_n$, then its maximizer over $\mathcal{M}_n$, i.e. the MLE, must be on the boundary of $\mathcal{M}_n$.

In our analysis of boundary strata we restricted attention to nondegenerate tensors in Δ_{2^n-1}. The lemma below ensures that by looking at the data U we can detect when the MLE is going to lie in this nondegenerate part, and so, when we can apply Theorem 3.6. It implies that if the sample proportions tensor $Q = \frac{1}{N}U$ lies outside the degenerate part of Δ_{2^n-1}, then the MLE $\hat{P}$ over $\mathcal{M}_n$ will also be nondegenerate.

Lemma 4.1. *Let $\mathcal{M}$ be a model in Δ_{k-1} for some $k \geq 1$ and let $Q = \frac{1}{N}U$ be the sample proportions for data U. Then if the MLE $\hat{P}$ for U exists, the support of Q is contained in the support of $\hat{P}$.*

Proof. The MLE is the constrained maximizer over $\mathcal{M}$ of the log-likelihood

$$\sum_{i=1}^{k} u_i \log P_i \;=\; \sum_{i \in \mathrm{supp}(Q)} u_i \log P_i.$$

It is equal to $-\infty$ at all points P with $P_i = 0$ for some $i \in \mathrm{supp}(Q)$.

4.1. General results

In order to solve the optimization problem for the log-likelihood (5), one can compute all critical points of $\ell(\theta)$ over the interior and all boundary strata of $\mathcal{M}_n$. For many parametrized statistical models the equations defining these critical points are just rational functions in the parameter vector θ. This is the case for the latent class models that we study in this paper. We will call the number of **complex** critical points of $\ell(\theta)$ over a model for generic data U the *maximum likelihood degree* (ML-degree) of that model. The ML-degree for general algebraic statistical models were introduced in [7] and [19]. In particular, it was shown that the ML-degree of such a model is a stable number. We will use the ML-degrees of the boundary strata of $\mathcal{M}_n$ as an indication for the complexity of solving the maximum likelihood estimation problem. For instance, if the ML-degree is ≤ 4, then one can express the MLE with closed form formulas as a function of U. In particular, if the ML-degree is equal to one, then the MLE can be expressed as a rational function of U.

In order to solve the constrained optimization problem of maximizing the likelihood function, one can employ the following simple scheme:

(a) For each stratum S of $\mathcal{M}_n$ list the critical points of the log-likelihood function constrained to its closure $\overline{S}$.

(b) Pick the best point from the list of those critical points that lie in $\mathcal{M}_n$.

Our first observation for this procedure is that we never need to check all the strata to find a global maximum. To see this consider the poset of the boundary stratification as described in the previous section. In our search for the global maximum we start from the maximal element of the poset and move recursively down. If a global maximum over the closure $\overline{S}$ lies in the stratum S, there is no need to optimize over any stratum $S' \preceq S$. As shown below, for many strata the MLE is guaranteed to lie inside $\mathcal{M}_n$.

A second observation is that maximizing the log-likelihood over most of the strata is challenging. The defining constraints correspond to complicated context specific independence constraints [6], and there is as yet no general theory on how to optimize over

these models exactly. There are, however, several exceptions including the strata considered in Section 3. We begin by introducing notation used below: For the data tensor $U = (u_{i_1 \cdots i_n})$ denote by $U^{(s,t)} = (u_{ij}^{(s,t)})$ the matrix whose (i,j)-th entry is the count of the event $\{X_s = i, X_t = j\}$ and by $U^{(s)} = (u_i^{(s)})$ the vector whose entries are the counts of the event $\{X_s = i\}$.

(a) *Codimension one strata (type (2), $k = 2n$).* Each tensor on one of these $2n$ strata corresponds to a context specific independence model, such as where $X_2, \ldots, X_n$ are independent conditionally on $\{X_1 = 1\}$. The ML-degree of the corresponding conditional model is one; hence, the MLE is expressed as a rational function of the data:

$$\hat{p}_{1j_2 \cdots j_i \cdots j_n} \quad = \quad \frac{u_{1j_2}^{(12)} u_{1j_3}^{(13)} \cdots u_{1j_n}^{(1n)}}{N {u_1^{(1)}}^{n-2}}.$$

After normalization, the other slice is a tensor from the model $\mathcal{M}_{n-1}$. Therefore $\hat{p}_{2j_2 \cdots j_i \cdots j_n}$ can be computed by employing any procedure that can be used for $\mathcal{M}_{n-1}$. For instance, in the next section we derive a closed form formula for the maximizer on each boundary stratum of $\mathcal{M}_3$. Hence, in the case of $\mathcal{M}_4$ all codimension one strata will also have closed form formulas.

(b) *The exceptional codimension two strata of type (3).* As noted in Section 3, these strata correspond to simple graphical models over graphs like that in Figure 2. The ML-degree of this model is one; hence, the MLE is expressed as a rational function of the data (also see [23, Section 4.4.2]):

$$\hat{p}_{j_1 j_2 \cdots j_i \cdots j_n} \quad = \quad \frac{u_{j_1 j_2}^{(12)} u_{j_1 j_3}^{(13)} \cdots u_{j_1 j_n}^{(1n)}}{N {u_{j_1}^{(1)}}^{n-2}}.$$

This point is always guaranteed to lie in $\mathcal{M}_n$ and so we never have to check strata that lie below that in the Hasse diagram defined in the previous section. These are the $\binom{n}{2}$ strata of type (4) and the type (5) stratum. Nevertheless, optimizing over these special strata is simple so we describe it next.

(c) *The $(n+1)$-dimensional strata of type (4).* These strata correspond to graphical models with one edge and $n-2$ disconnected nodes. The ML-degree of this model is one. For example, if 1 and 2 are connected by an edge and all other nodes are disconnected, the MLE is

$$\hat{p}_{j_1 j_2 j_3 \cdots j_n} \quad = \quad \frac{1}{N^{n-1}} u_{j_1 j_2}^{(12)} u_{j_3}^{(3)} \cdots u_{j_n}^{(n)}.$$

(d) *The n-dimensional stratum of type (5).* This stratum corresponds to the full-independence model and has ML-degree one. The MLE over this stratum is simply

$$\hat{p}_{j_1 j_2 \cdots j_i \cdots j_n} \quad = \quad \frac{1}{N^n} u_{j_1}^{(1)} u_{j_2}^{(2)} \cdots u_{j_n}^{(n)}.$$

There is one exceptional case, $n = 3$, when *all* strata are defined by binomial equations, in which case the closure of each stratum corresponds to a log-linear model. The MLE is therefore uniquely given and can be easily computed. We discuss this in more detail in the following subsection.

4.2. Maximum Likelihood Estimation for $\mathcal{M}_3$

The binary latent class model for three observed variables in the probability simplex Δ_7 is parametrized by

$$p_{ijk} = \lambda_1 a_{1i} b_{1j} c_{1k} + \lambda_2 a_{2i} b_{2j} c_{2k}$$

where

$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \quad B = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \quad C = \begin{pmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{pmatrix},$$

are stochastic matrices. We will depict the resulting tensor P as

$$\lambda_1 \left(\begin{array}{cc|cc} a_{11}b_{11}c_{11} & a_{11}b_{11}c_{12} & a_{12}b_{11}c_{11} & a_{12}b_{11}c_{12} \\ a_{11}b_{12}c_{11} & a_{11}b_{12}c_{12} & a_{12}b_{12}c_{11} & a_{12}b_{12}c_{12} \end{array} \right) + \lambda_2 \left(\begin{array}{cc|cc} a_{21}b_{21}c_{21} & a_{21}b_{21}c_{22} & a_{22}b_{21}c_{21} & a_{22}b_{21}c_{22} \\ a_{21}b_{22}c_{21} & a_{21}b_{22}c_{22} & a_{22}b_{22}c_{21} & a_{22}b_{22}c_{22} \end{array} \right).$$

$\mathcal{M}_3$ has dimension 7 with the following stratification given by Theorem 3.6, c.f. Figure 3.

1. The interior of $\mathcal{M}_3$ has dimension 7. Its Zariski closure is the linear space $\{p : \sum p_{ijk} = 1\}$. Its ML-degree is one and the MLE is computed by

$$\hat{p}_{ijk} = \frac{u_{ijk}}{u_{+++}} \qquad i, j, k = 1, 2.$$

2. There are six 6-dimensional strata. Each is obtained as the image of those matrices where one entry in the first row of A, B, or C is set to 0, such as $a_{11} = 0$. The resulting tensor is of the form

$$\lambda_1 \left(\begin{array}{cc|cc} 0 & 0 & b_{11}c_{11} & b_{11}c_{12} \\ 0 & 0 & b_{12}c_{11} & b_{12}c_{12} \end{array} \right) + \lambda_2 \left(\begin{array}{cc|cc} a_{21}b_{21}c_{21} & a_{21}b_{21}c_{22} & a_{22}b_{21}c_{21} & a_{22}b_{21}c_{22} \\ a_{21}b_{22}c_{21} & a_{21}b_{22}c_{22} & a_{22}b_{22}c_{21} & a_{22}b_{22}c_{22} \end{array} \right).$$

Hence its first slice is a rank one matrix whereas its second slice is generically a rank two matrix. The Zariski closure is defined by $p_{111}p_{122} - p_{112}p_{121}$ (together with $\sum p_{ijk} - 1$) and forms a log-linear model. From the statistical point of view this stratum corresponds to the context specific independence model, where X_2 is independent of X_3 given $\{X_1 = 1\}$. Its ML-degree is one and the MLE is computed by

$$\hat{p}_{1jk} = \frac{u_{1j+} \cdot u_{1+k}}{u_{1++} \cdot u_{+++}}, \qquad \hat{p}_{2jk} = \frac{u_{2jk}}{u_{+++}} \qquad j, k = 1, 2.$$

There are fifteen boundary strata of dimension 5 arising from types (2) and (3).

3a. There are twelve strata of the first kind arising as type (2) strata. Each is obtained as the image of two types of parameters. The first type of parameters has one entry in the first (or second) row of two matrix parameters equal to zero. The canonical example is $a_{11} = 0$ and $b_{11} = 0$. The resulting tensor is of the form

$$\lambda_1 \left(\begin{array}{cc|cc} 0 & 0 & 0 & 0 \\ 0 & 0 & c_{11} & c_{12} \end{array} \right) + \lambda_2 \left(\begin{array}{cc|cc} a_{21}b_{21}c_{21} & a_{21}b_{21}c_{22} & a_{22}b_{21}c_{21} & a_{22}b_{21}c_{22} \\ a_{21}b_{22}c_{21} & a_{21}b_{22}c_{22} & a_{22}b_{22}c_{21} & a_{22}b_{22}c_{22} \end{array} \right).$$

The second type comes from parameters where one of the matrices has rank one. The corresponding example for the above boundary stratum is when $\text{rank}(C) = 1$, in which case, $c_{11} = c_{21} = c$ and $c_{12} = c_{22} = \bar{c}$, since C is a stochastic matrix. The resulting tensor is of the form

$$\lambda_1 \left(\begin{array}{cc|cc} a_{11}b_{11}c & a_{11}b_{11}\bar{c} & a_{12}b_{11}c & a_{12}b_{11}\bar{c} \\ a_{11}b_{12}c & a_{11}b_{12}\bar{c} & a_{12}b_{12}c & a_{12}b_{12}\bar{c} \end{array} \right) + \lambda_2 \left(\begin{array}{cc|cc} a_{21}b_{21}c & a_{21}b_{21}\bar{c} & a_{22}b_{21}c & a_{22}b_{21}\bar{c} \\ a_{21}b_{22}c & a_{21}b_{22}\bar{c} & a_{22}b_{22}c & a_{22}b_{22}\bar{c} \end{array} \right).$$

Two (overlapping) slices of both of these tensors are rank one matrices, namely, the slices corresponding to $\begin{pmatrix} p_{111} & p_{112} \\ p_{121} & p_{122} \end{pmatrix}$ and $\begin{pmatrix} p_{111} & p_{112} \\ p_{211} & p_{212} \end{pmatrix}$. The Zariski closure is defined by the 2-minors of $\begin{pmatrix} p_{111} & p_{121} & p_{211} \\ p_{112} & p_{122} & p_{212} \end{pmatrix}$, and it corresponds to two context specific independence constraints. Its ML-degree is one and the MLE is computed by

$$\hat{p}_{ijk} = \frac{u_{ij+} \cdot (u_{++k} - u_{22k})}{(u_{+++} - u_{221} - u_{222}) \cdot u_{+++}} \quad ijk \neq 221, 222 \qquad \hat{p}_{22k} = \frac{u_{22k}}{u_{+++}} \quad k = 1, 2$$

3b. There are three of the second kind (type (3)). Each comes from parameters where one of the matrices A, B, C is the identity matrix. The canonical example is $a_{12} = 0$ and $a_{21} = 0$. The resulting tensor is of the form

$$\lambda_1 \left(\begin{array}{cc|cc} b_{11}c_{11} & b_{11}c_{12} & 0 & 0 \\ b_{12}c_{11} & b_{12}c_{12} & 0 & 0 \end{array} \right) + \lambda_2 \left(\begin{array}{cc|cc} 0 & 0 & b_{21}c_{21} & b_{21}c_{22} \\ 0 & 0 & b_{22}c_{21} & b_{22}c_{22} \end{array} \right).$$

Two parallel slices of these tensors are each rank one matrices, namely, the slices corresponding to $\begin{pmatrix} p_{111} & p_{112} \\ p_{121} & p_{122} \end{pmatrix}$ and $\begin{pmatrix} p_{211} & p_{212} \\ p_{212} & p_{222} \end{pmatrix}$. The Zariski closure is defined by $p_{111}p_{122} - p_{112}p_{121}$ and $p_{211}p_{222} - p_{212}p_{221}$, and it corresponds to conditional independence of X_2 and X_3 given X_1. As indicated in the end of Section 3, the ML degree is one and the MLE is computed by

$$\hat{p}_{ijk} = \frac{u_{ij+} \cdot u_{i+k}}{u_{i++} \cdot u_{+++}} \quad i, j, k = 1, 2$$

4a. There are eight 4-dimensional strata of type (2). They are defined by the image of matrices where the same entry of the top row of A, B, C is zero. The canonical example is $a_{11} = b_{11} = c_{11} = 0$. The resulting tensor is of the form

$$\lambda_1 \left(\begin{array}{cc|cc} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right) + \lambda_2 \left(\begin{array}{cc|cc} a_{21}b_{21}c_{21} & a_{21}b_{21}c_{22} & a_{22}b_{21}c_{21} & a_{22}b_{21}c_{22} \\ a_{21}b_{22}c_{21} & a_{21}b_{22}c_{22} & a_{22}b_{22}c_{21} & a_{22}b_{22}c_{22} \end{array} \right).$$

The Zariski closure is also a log-linear model whose design matrix A can be chosen to be

$$A = \begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

where the columns correspond to $p_{111}, p_{112}, p_{121}, p_{122}, p_{211}, p_{212}, p_{221}, p_{222}$. The defining equations are given by the ideal

$$I_2 \begin{pmatrix} p_{111} & p_{121} & p_{211} \\ p_{112} & p_{122} & p_{212} \end{pmatrix} + I_2 \begin{pmatrix} p_{111} & p_{121} \\ p_{112} & p_{122} \\ p_{211} & p_{221} \end{pmatrix}$$

which is minimally generated by five quadrics. The ML-degree is two and the MLE is computed by choosing one of the two solutions obtained as follows. First $\hat{p}_{222} = \frac{u_{222}}{u_{+++}}$. Then let

$$\alpha = \frac{u_{111} + u_{112} - u_{221}}{u_{+++}} \qquad \beta = \frac{u_{121} + u_{122} + u_{221}}{u_{+++}}$$
$$\gamma = \frac{u_{211} + u_{212} + u_{221}}{u_{+++}} \qquad \delta = \frac{u_{111} + u_{121} + u_{211} + u_{221}}{u_{+++}}.$$

Then for each root $\hat{p}_{221}$ of

$$\delta p_{221}^2 - [(\alpha+\gamma)(\alpha+\beta) + \delta(\gamma+\beta)]p_{221} + \beta\gamma\delta = 0$$

compute

$$\begin{aligned}
\hat{p}_{212} &= \frac{\delta}{\alpha+\gamma}\hat{p}_{221} + \left(\gamma - \frac{\gamma\delta}{\alpha+\gamma}\right) \\
\hat{p}_{211} &= -\hat{p}_{212} - \hat{p}_{221} + \gamma \\
\hat{p}_{122} &= \frac{\delta}{\alpha+\beta}\hat{p}_{221} + \left(\beta - \frac{\beta\delta}{\alpha+\beta}\right) \\
\hat{p}_{121} &= -\hat{p}_{122} - \hat{p}_{221} + \beta \\
\hat{p}_{111} &= -\hat{p}_{121} - \hat{p}_{211} - \hat{p}_{221} + \delta \\
\hat{p}_{112} &= -\hat{p}_{111} + \hat{p}_{221} + \alpha.
\end{aligned}$$

Note that the computations should be done in the exact order given above.

4b. There are three 4-dimensional strata of type (4). They are obtained by letting one of the matrices A, B, C have rank one. A canonical example is where $a_{21} = a_{11} = a$, $a_{22} = a_{12} = \bar{a}$. The resulting tensor is of the form

$$\lambda_1 \left(\begin{array}{cc|cc} ab_{11}c_{11} & ab_{11}c_{12} & \bar{a}b_{11}c_{11} & \bar{a}b_{11}c_{12} \\ ab_{12}c_{11} & ab_{12}c_{12} & \bar{a}b_{12}c_{11} & \bar{a}b_{12}c_{12} \end{array}\right) + \lambda_2 \left(\begin{array}{cc|cc} ab_{21}c_{21} & ab_{21}c_{22} & \bar{a}b_{21}c_{21} & \bar{a}b_{21}c_{22} \\ ab_{22}c_{21} & ab_{22}c_{22} & \bar{a}b_{22}c_{21} & \bar{a}b_{22}c_{22} \end{array}\right)$$

As indicated in the end of Section 3, the ML degree is one and the MLE is computed by

$$\hat{p}_{ijk} = \frac{u_{ij+} \cdot u_{++k}}{u_{+++}^2}$$

5. There is one stratum of dimension three formed by rank one tensors, also known as the independence model on three binary random variables. This is a toric model and has ML degree one where the ML estimate is computed by

$$\hat{p}_{ijk} = \frac{u_{i++} \cdot u_{+j+} \cdot u_{++k}}{u_{+++}^3}.$$

4.3. Simulations

The exact maximum likelihood estimation for $\mathcal{M}_3$ gives us valuable insight into the geometry of the likelihood function for the latent class models. In this subsection we report on simulations that were designed to unearth this geometry. We also obtain a new perspective into the performance of the EM-algorithm.

(a) We say that a point $P \in \Delta_7$ lies in the attraction basin of a stratum S, if, given that the sample proportions tensor is P, the global maximum of the likelihood function lies in S. In our first simulation we approximate the relative volumes of the attraction basins of each stratum. Attraction basins for strata of type (4) and (5) are lower dimensional and so have volume zero.

We run 10^6 iterations, each time sampling P uniformly from Δ_7 and then sampling data of size $N = 1000$ from P. We use the resulting data tensor to find the MLE. Table 1 reports our findings. In 8.38% of cases, the MLE lies in the interior of $\mathcal{M}_3$. Quite interestingly, the fifteen 5-dimensional strata attract almost 50% of the points. In particular, the three special strata of type (3) attract 17.29% of the points so each of them attracts approximately 6%. This is almost as much as the interior attracts, and virtually the same as each codimension one stratum. Since we are trying to estimate the attraction basin volumes, we omitted the strata of type (4) and (5) from the table. In principle, an attraction basin of zero measure could still contain points that correspond to tables with integer entries, leading to a positive probability of the MLE lying on the stratum for data generated as counts. However, this did not happen in any of our simulations for Table 1.

Table 1

Relative volume of MLE attraction basins of strata in $\mathcal{M}_3$ for data uniformly distributed over Δ_7.

1× 7-dim	6× 6-dim	12× 5a-dim	3× 5b-dim	8× 4a-dim
8.38	36.24	29.75	17.29	8.34

The fact that codimension two strata attract more points than the interior and the codimension one strata together may be a bit counterintuitive at first, but follows directly

from the geometry of the model. The log-likelihood function is a strictly concave function over Δ_7 with the unique maximum given by the sample proportions. Its level sets are convex and centered around the sample proportions $Q = \frac{1}{N}U$. On the other hand, $\mathcal{M}_3$ is highly concave, as illustrated by its 3-dimensional linear section in Figure 1 of [2]. It is then natural to expect that lower-dimensional strata have higher probability of containing the global maximum as long as the sample proportions lie outside of $\mathcal{M}_3$. In the next simulation, we argue that this is not a desirable feature of the latent class model.

(b) Suppose that the true data generating distribution lies in $\mathcal{M}_3$ and the corresponding parameters are $\lambda_1 = \lambda_2 = \frac{1}{2}$ and

$$A = B = C = \begin{bmatrix} 1-\epsilon & \epsilon \\ \epsilon & 1-\epsilon \end{bmatrix} \qquad \text{for } \epsilon \in (0, 0.5].$$

If ϵ is small, all variables are closely correlated with the unobserved variable. On the other extreme, if $\epsilon = 0.5$, all variables are independent of the unobserved variable. We generate N samples from the given distribution with a fixed ϵ and compute the MLE, repeating this 10,000 times. We start with $N = 1000$ which is a large number for such a small contingency table. In Table 2 we see that for ϵ close to 0.5 the probability of the MLE landing in the interior of $\mathcal{M}_3$ is small despite the fact that the data generating distribution lies in the model and that N is very large. This means that, even when the data generating distribution lies in the model, with high probability we can expect estimates to lie on the boundary. This obviously becomes more dramatic for smaller values of $N = 100$ and $N = 50$, see Table 3 and Table 4 respectively. In the last case, even for small values of ϵ, there is a high probability of hitting the boundary. This shows that the latent class models must be used with caution, especially if correlations between variables are small and the sample size is relatively small. Finally, we note that in producing the last row of Table 4 we observed some MLEs on the 3-dimensional strata of rank one tensors. This happens when the data tensor has rank one. Because these MLEs are also MLEs over the strata 5b, we report them there.

Table 2

Relative volume of MLE attraction basins of strata in $\mathcal{M}_3$ for the special generating distributions given by ϵ. Sample size $N = 1000$, number of iterations 10000.

ϵ	1× 7-dim	6× 6-dim	12× 5a-dim	3× 5b-dim	8× 4a-dim
0.5	12.02	47.59	22.09	13.06	5.24
0.4	34.52	43.87	12.13	7.94	1.54
0.3	99.32	0.67	0.01	0.00	0.00
0.2	100	0	0	0	0
0.1	100	0	0	0	0

(c) From the practical point of view it is of interest to study the performance of the EM algorithm, for which no realistic global convergence guarantees are known; see [4]

Table 3
Same as in Table 2 but with sample size $N = 100$.

ϵ	1× 7-dim	6× 6-dim	12× 5a-dim	3× 5b-dim	8× 4a-dim
0.5	10.72	45.97	22.92	14.35	6.04
0.4	12.15	46.07	21.29	15.27	5.22
0.3	38.00	43.62	10.84	6.36	1.18
0.2	80.53	17.92	1.60	0.32	0.03
0.1	90.02	9.54	0.3	0.13	0.01

Table 4
Same as in Table 2 but with sample size $N = 50$.

ϵ	1× 7-dim	6× 6-dim	12× 5a-dim	3× 5b-dim	8× 4a-dim
0.5	10.52	45.74	23.33	14.3	6.06
0.4	10.83	45.24	23.36	14.67	5.90
0.3	21.59	47.16	17.11	11.49	2.65
0.2	51.84	38.72	5.87	3.25	0.32
0.1	48.59	39.37	8.33	2.42	1.29

for a more detailed description of the problem. In our simulations to this end, we first generate our data in the same scenario as above with $\lambda_1 = \lambda_2 = \frac{1}{2}$, $\epsilon = 0.1, \ldots, 0.5$, and for sample sizes $N = 50, 100, 1000$. We report how many times the EM algorithm was not able to find the global optimum in less than 10 reruns. Given how simple and low-dimensional the model is, we think of 10 reruns already as a big number. Our main findings are summarized in Figure 4. When the sample size is large ($N = 1000$) this proportion is small if $\epsilon = 0.02, 0.05, 0.1, 0.2, 0.3$. However, for higher ϵ in more than half cases the EM algorithm was not able to find the global optimum. If $N = 50$ the results are even more interesting. Note that for $\epsilon = 0.4, 0.5$ the situation actually looks better than for $N = 1000$. This is somewhat counterintuitive at first but easy to explain. High values of ϵ correspond to ill-behaved distributions (close to singularities). If N is very high, the sample distribution lies close, and hence it is also ill-behaved, resulting in a complicated likelihood function. If the sample size is small, the variance of the sample distribution is much higher, so with relatively high probability the sample distribution will be far and better-behaved. In other words, if the correlations between variables are really small, smaller samples may lead to a better-behaved likelihood than big samples. For completeness of our discussion we repeat the same computations for a less symmetric set-up where $\lambda_1 = \frac{1}{5}$ but the results were very similar and will not be reported here.

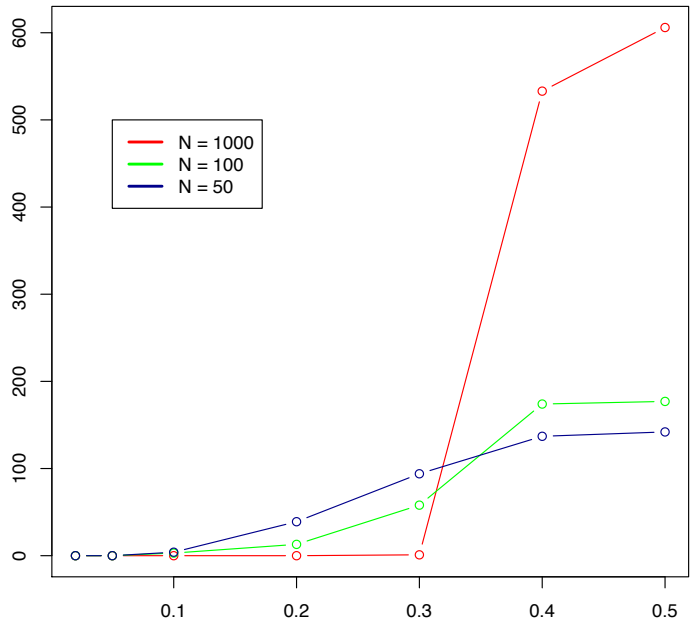

FIGURE 4: *The numbers of non-convergers in the EM-algorithm for 1000 experiments and 10 reruns of the EM algorithm for each experiment depending on the parameters defining the data-generating distribution. The x-axis displays values of ϵ.*

4.4. EM attraction basins for $3 \times 3 \times 2$ tensors of rank$_+ \leq 3$

We do not have a complete description of the boundary strata for tensors of nonnegative rank 3, nor formulas for MLEs. Thus, we present the results of our simulations for $3 \times 3 \times 2$ tensors with rank$_+ \leq 3$, denoting the matrix parameters of appropriate format by A, B, and C. This model, denoted by $\mathcal{M}^*$, is a full-dimensional, proper subset of Δ_{17} (i.e. with Zariski closure the full ambient space as in the case of $\mathcal{M}_3$). We are interested in giving an estimate for the relative volume of $\mathcal{M}^*$ in Δ_{17} and in obtaining some preliminary understanding of attraction basins for distributions sampled from Δ_{17} under EM.

We performed two tests. For an arbitrary distribution $P \in \Delta_{17}$, we ran EM from ten different starting points, recorded the parameters $\theta_0 \in \Theta$ to which EM converged, and took the optimal estimate. Without a full description of the boundary strata of $\mathcal{M}^*$, we classified the EM estimate into four categories: 1) the EM estimate θ_0 contains strictly positive entries; 2) the EM estimate θ_0 contains exactly one zero entry in a 3×3 stochastic matrix; 3) the EM estimate θ_0 contains exactly one zero entry in the 3×2 stochastic matrix; 4) the EM estimate θ_0 contains exactly k zero entries for $k \in \{2, ..., 11\}$. The idea is that the numbers of EM estimates per category give approximations to which points of Θ, either interior or on a boundary face of Θ, the EM estimates are drawn. Concretely, these numbers are used to estimate respectively

1. the relative volume of $\mathcal{M}^* \subsetneq \Delta_{17}$;

2. the EM attraction basin proportion for the 6 irreducible components of the algebraic

boundary given by a single zero in a 3×3 stochastic matrix A or B;

3. the EM attraction basin proportion for the 2 irreducible components of the algebraic boundary given by a single zero in the 3×2 stochastic matrix C;

4. the EM attraction basin proportions for intersections of k facets of Θ.

For 10^6 iterations, the proportions (given as percentages) of these EM attraction basins are given in Table 5, where $1a$-codim corresponds to the relative volume of category (2) and $1b$-codim to the relative volume of category (3). We separated categories (2) and (3), since (3) corresponds to a context specific independence model, but (2) does not.

We note that the highest concentration of estimates is in the faces of Θ of codimension 4, though we have no insight as to why this is the case. Also the relative volume of $\mathcal{M}^* \subsetneq \Delta_{17}$, filling out only approximately .019% of Δ_{17} is remarkably small, particularly when compared to relative volume estimates for $\mathcal{M}_3$ and $\mathcal{M}_{3,3}$.

As a second test, we ran EM for the same $P \in \Delta_{17}$, but with 10^4 different starting points. As expected, EM converged to many local optima on the nonconvex $\mathcal{M}^*$, with a majority (almost 76%) in the codim-4 stratum.

Table 5

Relative volume of EM attraction basins of strata in $\mathcal{M}^*$ using 10 different starting parameters for 10^6 uniformly distributed points over Δ_{17}.

0-codim	$1a$-codim	$1b$-codim	2-codim	3-codim	4-codim
0.019	0.2845	0.0621	3.4814	17.0098	40.1676

5-codim	6-codim	7-codim	8-codim	9-codim	10-codim	11-codim
25.7120	11.2486	1.7677	0.2249	0.0199	0.0025	0

5. EM fixed point ideals

It is well-known that the EM algorithm does not guarantee convergence to the global optimum of the likelihood function. In this section, we study the EM fixed point ideal introduced in [22] that eliminates this drawback. An EM fixed point for an observed data tensor U is a parameter vector in Θ which stays fixed after one iteration of the EM algorithm. The set of EM fixed points includes the candidates for the global maxima of the likelihood function; see Lemma 5.2. The solution set of the EM fixed point ideal contains all the EM fixed points, in particular, all the global maxima of the likelihood function. Hence, computing the solution set of the EM fixed ideal allows the computation of all the global maxima for the likelihood function. Moreover, for a given model $\mathcal{M}$, the EM fixed point ideal consists of the equations defining all EM fixed points for *any* data tensor U.

Therefore, for a given $\mathcal{M}$, it has to be computed only once. After this computationally intensive task, extracting the MLE for any given data tensor U is relatively easy.

After first describing the equations of the EM fixed point ideal for $\mathcal{M}_3$ in Proposition 5.3, we present the full prime decomposition of this ideal in Theorem 5.4. We illustrate two uses of this decomposition. First, we show that using the components of the prime decomposition one can automatically recover the formulas for the maximum likelihood estimator for various strata that we presented in Section 4.2. Second, we point out that the relevant components of this decomposition that contain entries of stochastic parameter matrices correspond precisely to the boundary strata of $\mathcal{M}_3$, also reported in Section 4.2. This hints at the usefulness of the EM fixed point ideal for the discovery of such boundary strata. In fact, we showcase this discovery process by computing the decomposition of the EM fixed point ideal of $\mathcal{M}_{3,3}$. The components we get give the boundary stratification of $\mathcal{M}_{3,3}$ as reported in [29].

We present a version of the EM algorithm adapted to latent class models with three observed variables in Algorithm 5.1. We no longer assume that the observed or hidden variables are binary. We let X_1, X_2, X_3 be the observed random variables with d_1, d_2, d_3 states, respectively, and we assume that the hidden variable takes values in $\{1, \ldots, r\}$. We denote this model by $\mathcal{M}_{d_1 \times d_2 \times d_3, r}$. Our presentation is based on [28, Section 1.3] and [22, Algorithm 1].

Algorithm 5.1. EM algorithm for the latent class model with three observed variables
Input: Observed data tensor $U \in \mathbb{Z}^{d_1 \times d_2 \times d_3}$.
Output: A proposed maximum $\hat{P} \in \Delta_{d_1 d_2 d_3 - 1}$ of the log-likelihood function ℓ on the model $\mathcal{M}_{d_1 \times d_2 \times d_3, r}$.
Step 0: Initialize randomly $(\lambda_1, \ldots, \lambda_r) \in \Delta_{r-1}$, $(a_{i1}, \ldots, a_{id_1}) \in \Delta_{d_1 - 1}$, $(b_{i1}, \ldots, b_{id_2}) \in \Delta_{d_2 - 1}$, and $(c_{i1}, \ldots, c_{id_3}) \in \Delta_{d_3 - 1}$ for $i = 1, \ldots, r$.
Run the E-step and M-step until the entries of $P \in \Delta_{d_1 d_2 d_3 - 1}$ converge.
E-Step: *Estimate the hidden data:*
Set $v_{lijk} := \frac{\lambda_l a_{li} b_{lj} c_{lk}}{\sum_{l=1}^{r} \lambda_l a_{li} b_{lj} c_{lk}} u_{ijk}$ for $l = 1, \ldots, r$, $i = 1, \ldots, d_1$, $j = 1, \ldots, d_2$, and $k = 1, \ldots, d_3$.
M-Step: *Maximize the log-likelihood function of the model with complete data using the estimates for the hidden data from the E-step:*
Set $\lambda_l := \sum_{i=1}^{d_1} \sum_{i=1}^{d_2} \sum_{i=1}^{d_3} v_{ijkl} / u_{+++}$ for $l = 1, ..., r$.
Set $a_{li} := \sum_{j=1}^{d_2} \sum_{k=1}^{d_3} v_{ijkl} / (u_{+++} \lambda_l)$ for $l = 1, \ldots, r$, $i = 1, \ldots, d_1$.
Set $b_{lj} := \sum_{i=1}^{d_1} \sum_{k=1}^{d_3} v_{ijkl} / (u_{+++} \lambda_l)$ for $l = 1, \ldots, r$, $j = 1, \ldots, d_2$.
Set $c_{lk} := \sum_{i=1}^{d_1} \sum_{j=1}^{d_2} v_{ijkl} / (u_{+++} \lambda_l)$ for $l = 1, \ldots, r$, $k = 1, \ldots, d_3$.
Update *the joint distribution for the latent class model:*
Set $p_{ijk} := \sum_{l=1}^{r} \lambda_l a_{li} b_{lj} c_{lk}$ for $i = 1, \ldots, d_1$, $j = 1, \ldots, d_2$, $k = 1, \ldots, d_3$.
Return P.

An *EM fixed point* for an observed data tensor U is an element of $\Theta := \Delta_{r-1} \times (\Delta_{d_1 - 1})^r \times (\Delta_{d_2 - 1})^r \times (\Delta_{d_3 - 1})^r$ which stays fixed after one E-step and M-step of the EM-algorithm with the input U.

Lemma 5.2. *Any $\theta \in \Theta$ to which the EM-algorithm can converge is an EM fixed point.*

Proof. Denote the function defined by one step of the EM-algorithm by $\mathrm{EM}(\cdot)$. Pick an initial point $\theta^{(0)} \in \Theta$, and let $\theta^{(k+1)} = \mathrm{EM}(\theta^{(k)})$. Assuming that $\theta := \lim_{k\to\infty} \theta^{(k)}$ exists, then $\lim_k \theta^{(k+1)} = \lim_k \mathrm{EM}(\theta^{(k)})$, and since EM is continuous, we obtain $\theta = \mathrm{EM}(\theta)$.

Lemma 5.2 justifies the study of the set of the EM fixed points as this set contains all possible outputs of the EM algorithm. In [22, Section 3], the set of all EM fixed points of a latent class model with two observed variables is studied through the minimal set of polynomial equations that they satisfy. These equations are called the *EM fixed point equations.*

Proposition 5.3. *The EM fixed point equations for $2\times 2\times 2$-tensors of rank$_+ \leq 2$ on the parameter space Θ are*

$$a_{\ell i}\left(\sum_{j,k=1}^{2} r_{ijk} b_{\ell j} c_{\ell k}\right) = 0 \qquad \textit{for all} \quad \ell, i = 1,2,$$

$$b_{\ell j}\left(\sum_{i,k=1}^{2} r_{ijk} a_{\ell i} c_{\ell k}\right) = 0 \qquad \textit{for all} \quad \ell, j = 1,2,$$

$$c_{\ell k}\left(\sum_{i,j=1}^{2} r_{ijk} a_{\ell i} b_{\ell j}\right) = 0 \qquad \textit{for all} \quad \ell, k = 1,2,$$

where $[r_{ijk}] = \left[u_{+++} - \frac{u_{ijk}}{p_{ijk}}\right]$.

Proof. The proof is virtually identical to the proof of [22, Theorem 3.5].

We call the ideal generated by the equations in Proposition 5.3 the *EM fixed point ideal* and denote it by $\mathcal{F}$. This ideal is not prime and it defines a reducible variety. A minimal prime of $\mathcal{F}$ is called *relevant* if it contains none of the 8 polynomials $p_{ijk} = \sum_{\ell=1}^{2} a_{\ell i} b_{\ell j} c_{\ell k}$ and none of the six ideals $\langle a_{l1}, a_{l2}\rangle$, $\langle b_{l1}, b_{l2}\rangle$ and $\langle c_{l1}, c_{l2}\rangle$. Equivalently, an ideal is relevant, if not all of its solutions P has a coordinate that is identically zero, and after normalizing the parameters, it comes from stochastic matrices.

Theorem 5.4. *The radical of the EM fixed point ideal $\mathcal{F}$ for $\mathcal{M}_3$ has precisely* 63 *relevant primes consisting of* 9 *orbital classes.*

Proof. This proof follows the proof of [22, Theorem 5.5] in using the approach of cellular components from [10]. The EM fixed point ideal $\mathcal{F}$ is given by

$$\left\langle a_{\ell i}\left(\sum_{j,k=1}^{2} r_{ijk} b_{\ell j} c_{\ell k}\right), b_{\ell j}\left(\sum_{i,k=1}^{2} r_{ijk} a_{\ell i} c_{\ell k}\right), c_{\ell k}\left(\sum_{i,j=1}^{2} r_{ijk} a_{\ell i} b_{\ell j}\right) : i,j,k,l = 1,2\right\rangle.$$

Any prime ideal containing $\mathcal{F}$ contains either $a_{\ell i}$ or $\sum_{j,k=1}^{2} r_{ijk} b_{\ell j} c_{\ell k}$ for $\ell, i \in \{1,2\}$, and either $b_{\ell j}$ or $\sum_{i,k=1}^{2} r_{ijk} a_{\ell i} c_{\ell k}$ for $\ell, j \in \{1,2\}$, and either $c_{\ell k}$ or $\sum_{i,j=1}^{2} r_{ijk} a_{\ell i} b_{\ell j}$ for $\ell, k \in \{1,2\}$. We categorize all primes containing $\mathcal{F}$ according to the set S of parameters $a_{\ell i}$, $b_{\ell j}$, and $c_{\ell k}$ contained in them. The symmetry group acts on the parameters by permuting the rows of A, B, and C simultaneously, the columns of A, B, and C separately, and the matrices A, B, and C themselves. For each orbit that consists of relevant ideals, we pick one representative S and compute the *cellular component* $\mathcal{F}_S = ((\mathcal{F} + \langle S \rangle) : (\prod S^c)^\infty)$, where $S^c = \{a_{11}, \ldots, a_{22}, b_{11}, \ldots, b_{22}, c_{11}, \ldots, c_{22}\} \setminus S$. Next we remove all representatives S such that $\mathcal{F}_T \subset \mathcal{F}_S$ for a representative T in another orbit. For each remaining cellular component $\mathcal{F}_S$, we compute its minimal primes. In each case, we use either the `Macaulay2` `minimalPrimes` function or the linear elimination sequence from [13, Proposition 23(b)]. Finally, we remove those minimal primes of $\mathcal{F}_S$ that contain a cellular component $\mathcal{F}_T$ for a set T (not necessarily a representative) in another orbit. The remaining 9 minimal primes correspond to the rows of Table 6 and are uniquely determined by their properties. These are the set S, the degree and codimension, the ranks $rA = \text{rank}(A)$, $rB = \text{rank}(B)$, and $rC = \text{rank}(C)$ at a generic point. The 63 ideals are obtained when counting each orbit with its orbit size in the last column of Table 6.

Table 6
Minimal primes of EM fixed point ideal $\mathcal{F}$ for $2 \times 2 \times 2$-tensors of rank$_+$ 2.

Class S	**|S|**	a's	b's	c's	**deg**	**codim**	**rA**	**rB**	**rC**	**orbit**	**in Thm. 3.6**
$\{\emptyset\}$	0	0	0	0	60	7	1	1	1	1	3-diml. type 5
	0	0	0	0	48	7	2	2	1	1	4-diml. type 4
	0	0	0	0	48	7	2	1	2	1	4-diml. type 4
	0	0	0	0	48	7	1	2	2	1	4-diml. type 4
	0	0	0	0	1	8	2	2	2	1	7-diml. type 1
$\{a_{11}\}$	1	1	0	0	5	8	2	2	2	12	6-diml. type 2
$\{a_{11}, a_{22}\}$	2	2	0	0	25	8	2	2	2	6	5-diml. type 3
$\{a_{11}, b_{11}\}$	2	1	1	0	11	8	2	2	2	24	5-diml. type 2
$\{a_{11}, b_{11}, c_{11}\}$	3	1	1	1	23	8	2	2	2	16	4-diml. type 2

The rows of Table 6 correspond to different boundary strata in Theorem 3.6, and this correspondence is reported in the last column of the table. The orbit sizes in Table 6 are twice the number of corresponding strata in Corollary 3.7, except for the rows represented by $\{\emptyset\}$. This is because the ideal obtained by switching the rows of A, B and C is counted as distinct from the original ideal, though the tensors in the image of both sets of parameters are identical with parameters that differ only by label swapping. For example, the minimal prime represented by $\{a_{21}\}$ is one the 12 ideals in the orbit of the minimal prime represented by $\{a_{11}\}$, although $\{a_{11} = 0\}$ and $\{a_{21} = 0\}$ define the same boundary stratum.

In the next example we explain how to derive the EM fixed points and the potential MLEs from the former type of minimal primes of the EM fixed point ideal.

Example 5.5. Consider the minimal prime of the EM fixed point ideal corresponding to $a_{11} = a_{22} = 0$:

$$\begin{aligned} I_1 =\langle & a_{22}, a_{11}, r_{212}r_{221} - r_{211}r_{222}, c_{11}r_{221} + c_{12}r_{222}, b_{11}r_{212} + b_{12}r_{222}, c_{11}r_{211} + c_{12}r_{212}, \\ & b_{11}r_{211} + b_{12}r_{221}, r_{112}r_{121} - r_{111}r_{122}, c_{21}r_{121} + c_{22}r_{122}, b_{21}r_{112} + b_{22}r_{122}, \\ & c_{21}r_{111} + c_{22}r_{112}, b_{21}r_{111} + b_{22}r_{121}\rangle. \end{aligned}$$

We add to the ideal I_1 the ideal of the parametrization map

$$\begin{aligned} I_2 =\langle & -a_{21}b_{21}c_{21} + p_{111}, -a_{21}b_{21}c_{22} + p_{112}, -a_{21}b_{22}c_{21} + p_{121}, -a_{21}b_{22}c_{22} + p_{122}, \\ & - a_{12}b_{11}c_{11} + p_{211}, -a_{12}b_{11}c_{12} + p_{212}, -a_{12}b_{12}c_{11} + p_{221}, -a_{12}b_{12}c_{12} + p_{222}\rangle. \end{aligned}$$

Eliminating parameters $a_{11}, \ldots, c_{22}$ from $I_1 + I_2$, gives the ideal

$$\begin{aligned} J =\langle & p_{212}p_{221} - p_{211}p_{222}, r_{221}p_{221} + r_{222}p_{222}, r_{211}p_{221} + r_{212}p_{222}, r_{212}p_{212} + r_{222}p_{222}, \\ & r_{211}p_{212} + r_{221}p_{222}, r_{221}p_{211} + r_{222}p_{212}, r_{212}p_{211} + r_{222}p_{221}, r_{211}p_{211} - r_{222}p_{222}, \\ & p_{112}p_{121} - p_{111}p_{122}, r_{121}p_{121} + r_{122}p_{122}, r_{111}p_{121} + r_{112}p_{122}, r_{112}p_{112} + r_{122}p_{122}, \\ & r_{111}p_{112} + r_{121}p_{122}, r_{121}p_{111} + r_{122}p_{112}, r_{112}p_{111} + r_{122}p_{121}, r_{111}p_{111} - r_{122}p_{122}, \\ & r_{212}r_{221} - r_{211}r_{222}, r_{112}r_{121} - r_{111}r_{122}\rangle \end{aligned}$$

Finally, we substitute to the ideal J the expressions

$$r_{ijk} = u_{+++} - \frac{u_{ijk}}{p_{ijk}}$$

and clear the denominators. To obtain an estimate for p_{111}, we eliminate all other p_{ijk}. This gives the ideal generated by $p_{111}u_{1++}u_{+++} - u_{11+}u_{1+1}$. Hence

$$p_{111} = \frac{u_{11+}u_{1+1}}{u_{1++}u_{+++}},$$

as in Section 4.

We used the method in Example 5.5 to verify the formulas in Section 4.2 for MLEs on different strata for all cases besides the 3- and 4-dimensional strata. For the 3- and 4-dimensional strata, the elimination of p_{ijk}'s did not terminate.

Since the rows of Table 6 are in correspondence with the boundary strata of $\mathcal{M}_3$, we believe that the method of decomposing the EM fixed point ideal is useful for identifying boundary strata for models whose geometry is not as well understood as that of $\mathcal{M}_3$. We illustrate this idea with the decomposition of $\mathcal{M}_{3,3}$.

Theorem 5.6. *The radical of the EM fixed point ideal $\mathcal{F}$ for $\mathcal{M}_{3,3}$ has* 317 *relevant primes consisting of* 21 *orbital classes. The properties of these orbital classes are listed in Table 7.*

Table 7
Minimal primes of EM fixed point ideal $\mathcal{F}$ for $2 \times 2 \times 2$-tensors of rank$_+$ 3.

Set S	$\lvert S\rvert$	a's	b's	c's	**deg**	**cdim**	**rA**	**rB**	**rC**	**orbit**
$\{\emptyset\}$	0	0	0	0	121	10	1	1	1	1
	0	0	0	0	162	9	1	2	2	1
	0	0	0	0	162	9	2	1	2	1
	0	0	0	0	162	9	2	2	1	1
	0	0	0	0	38	10	2	2	2	6×1
	0	0	0	0	1	8	2	2	2	1
$\{a_{11}\}$	1	1	0	0	10	10	2	2	2	18
$\{a_{11}, a_{21}\}$	2	2	0	0	5	9	2	2	2	18
$\{a_{11}, b_{11}\}$	2	1	1	0	39	10	2	2	2	36
$\{a_{11}, a_{21}, a_{32}\}$	3	3	0	0	50	11	2	2	2	18
$\{a_{11}, b_{11}, c_{11}\}$	3	1	1	1	60	11	2	2	2	24
$\{a_{11}, a_{21}, b_{11}, b_{21}\}$	4	2	2	0	11	10	2	2	2	36
$\{a_{11}, a_{22}, b_{11}, b_{22}\}$	4	2	2	0	8	11	2	2	2	36
$\{a_{11}, a_{21}, b_{11}, b_{21}, c_{11}, c_{21}\}$	6	2	2	2	23	11	2	2	2	24
$\{a_{11}, a_{21}, b_{11}, b_{22}, c_{11}, c_{22}\}$	6	2	2	2	20	12	2	2	2	72
$\{a_{11}, a_{22}, b_{11}, b_{22}, c_{11}, c_{22}\}$	6	2	2	2	23	12	2	2	2	24

Some of the ideals listed in Table 7 have further constraints on the 3×2 stochastic matrices A, B and C that cannot be read off directly from the table. These constraints are:

1. One out of the six ideals of degree 38 corresponding to $\{\emptyset\}$ contains polynomials $a_{11}a_{22} - a_{12}a_{21}$, $b_{21}b_{32} - b_{22}b_{31}$ and $c_{11}c_{32} - c_{12}c_{31}$. Constraints for the rest of the five ideals are obtained by permuting simultaneously the rows of A, B and C.

2. The ideal corresponding to $\{a_{11}\}$ contains polynomials $b_{21}b_{32} - b_{22}b_{31}$ and $c_{21}c_{32} - c_{22}c_{31}$.

3. The ideal corresponding to $\{a_{11}, b_{11}\}$ contains the polynomial $c_{21}c_{32} - c_{22}c_{31}$.

4. The ideal corresponding to $\{a_{11}, a_{21}, a_{32}\}$ contains polynomials $b_{11}b_{22} - b_{12}b_{21}$ and $c_{11}c_{22} - c_{12}c_{21}$.

5. The ideal corresponding to $\{a_{11}, b_{11}, c_{11}\}$ contains polynomials $a_{21}a_{32} - a_{22}a_{31}$, $b_{21}b_{32} - b_{22}b_{31}$ and $c_{21}c_{32} - c_{22}c_{31}$.

The semialgebraic description, boundary stratification and closed formulas for MLEs for $\mathcal{M}_{3,3}$ are obtained in [29]. The boundary stratification poset for $\mathcal{M}_{3,3}$ agrees with the one for $\mathcal{M}_3$ in Figure 3. The parameters that yield different types of boundary strata for $\mathcal{M}_{3,3}$ are included in Table 7:

1. Interior: $\{\emptyset\}$ (A, B, C rank 2, no further constraints on A, B and C).

2. Codimension 1 strata: $\{a_{11}\}^*$, $\{a_{11}, a_{21}\}$.
3. Exceptional codimension 2 strata: $\{a_{11}, a_{21}, a_{32}\}^*$.
4. Codimension 2 strata: $\{a_{11}, b_{11}\}^*$, $\{a_{11}, a_{21}, b_{11}, b_{21}\}$.
5. Exceptional codimension 3 strata: $\{\emptyset\}^*$ (A, B or C rank 1).
6. Codimension 3 strata: $\{a_{11}, b_{11}, c_{11}\}^*$, $\{a_{11}, a_{21}, b_{11}, b_{21}, c_{11}, c_{21}\}$.
7. Unique codimension 4 stratum: $\{\emptyset\}^*$ (A, B and C rank 1).
8. Other: $\{\emptyset\}^*$ (A, B, C rank 2, further constraints on A, B and C), $\{a_{11}, a_{22}, b_{11}, b_{22}\}$, $\{a_{11}, a_{21}, b_{11}, b_{22}, c_{11}, c_{22}\}$, $\{a_{11}, a_{22}, b_{11}, b_{22}, c_{11}, c_{22}\}$.

A star indicates that besides setting the elements in the set to zero, further equation constraints on the parameters (either rank constraints from Table 7 or other constraints from the list above) are needed to define the stratum. Taking these further constraints into account, for a fixed type of boundary stratum, all parametrizations from Table 7 are minimal. All the rows of Table 7 that do not give boundary strata lie on the singular locus of $\mathcal{M}_{3,3}$.

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