

# New Results on Existence of a Class of Caputo Neutral Fractional Differential Equation Dependence on Lipschitz First Derivative

C. Monickpriya<sup>1</sup>, U. Karthik Raja<sup>2</sup>, D. Swathi<sup>3</sup>, V. Pandiyammal<sup>4</sup>

<sup>1,2</sup>Research Center & PG Department of Mathematics, The Madura College, Madurai-625 011, Tamilnadu, India.

<sup>3</sup>Department of Mathematics, P.K.N Arts and Science College, Madurai- 625 706, Tamilnadu, India.

<sup>4</sup>Department of Mathematics, Arulmigu Palaniandavar College of Arts and Culture, Palani -624601, Tamil Nadu, India.

<sup>2</sup>Correspondence Email:ukarthikraja@yahoo.co.in

## ABSTRACT

In this article, we discussed the existence and uniqueness solution for the class of Caputo fractional neutral functional differential equations with addiction on the Lipschitz first derivative conditions in Banach space. The result is established on Krasnoselskii's Fixed point theorem. As well as, an example is illustrate the results.

## INTRODUCTION

Fractional differential equation is broad and comprehensive assortment of many mathematical modelling in real world application for that many researchers extent their interest in fractional differential equations. It is proven that a paramount mathematical modeling in all manner of field such as neural network system [7], dynamics [13], engineering [9], medical and health science [8], medical image enhancement [5], viscoelacidity [2], modern mechanics [15,17], biological systems [3,4,11,12].

The neutral type functional differential equations depends on past and present values of the function, likewise to retarded differential equations, except it also depends on derivatives with delays. An enormous potential and applicability to solve the fractional differential equations in numerical accuracy so for that many authors gave existence results in neutral differential equations. The neutral differential equations have numerous important application in science and engineering particularly control theory is one of the interesting applications in neutral fractional system. The Initial value problem for a class of fractional neutral differential equations with infinite delay discussed by Benchohra et al [10]. For further research work yet, we have lot of proposed problems of neutral differential equations are exposed.

In this article we investigate the existence results for the IVP of fractional neutral system with boundedness is of the form

$$\begin{cases} ({}^c D^\alpha) \left( u(t) - f(t, u(t), u'(t, u(t))) \right) = g(t, u(t), u'(t, u(t))), t_0 \geq 0, 1 < \alpha < 2 \\ u_{t_0} = \varphi \end{cases} \quad (1)$$

Where  $({}^c D^\alpha)$  is the Caputo fractional derivative,  $f, g: [t_0, +\infty) \times C([-k, 0], \mathbb{R}^n) \times C([-k, 0], \mathbb{R}^n) \rightarrow \mathbb{R}^n$  are given continuous functions and  $\varphi \in C([-k, 0], \mathbb{R}^n)$ . In  $u \in C([t_0 - k, t_0 + m], \mathbb{R}^n)$  then for any  $t \in [t_0 - k, t_0 + m]$  then for  $\varpi \in [-k, 0]$  defined by  $u_t(\varpi) = u(t + \varpi)$ .

Consider  $\mathfrak{D}u(t) = u'(t, u(t))$ . Then (1) becomes

$$\begin{cases} ({}^c D^\alpha) \left( u(t) - f(t, u(t), \mathfrak{D}u(t)) \right) = g(t, u(t), \mathfrak{D}u(t)), t_0 \geq 0, 1 < \alpha < 2 \\ u_{t_0} = \varphi \end{cases} \quad (2)$$

This article is divided in the following sections: In section 2 we give the basic definitions, lemmas, theorems, which is we used in the upcoming section to resolve our main results. In the last section we discussed our main results.

## 2 PRELIMINARIES

In this section, we include the basic definitions, lemmas which we used throughout this paper. Let  $J \subset \mathbb{R}$  and denote  $C(J, \mathbb{R}^n)$  be the Banach space of all continuous functions from  $J$  into  $\mathbb{R}^n$  with the norm  $\|u\| = \sup_{t \in J} |u(t)|$  where  $|\cdot|$  represent the complete norm on  $\mathbb{R}^n$ .

**Definition 2.1** ([1.6]) The fractional integral of order  $\alpha$  for a function  $h$  is defined as

$$({}_a I^\alpha h)(t) = \frac{1}{\Gamma(\alpha)} \int_a^t (t-s)^{\alpha-1} h(s) ds$$

**Definition 2.2** ([1,6]) The R-L derivative of order  $\alpha$  is defined by

$$({}_a D^\alpha h)(t) = \frac{d}{dt} \left( \frac{1}{\Gamma(1-\alpha)} \int_a^t (t-s)^{-\alpha} h(s) ds \right)$$

**Remark 2.3** The ultimate property of R-L fractional derivative is that for  $t > t_0$  and  $\alpha > 0$  we have

$$D^\alpha (I^\alpha h(t)) = h(t)$$

**Definition 2.4** ([1,6]) For the function  $h$  in  $[a, b]$ , the Caputo fractional derivative of order  $\alpha$  is given by

$$({}_a^c D^\alpha h)(t) = \frac{1}{\Gamma(n-\alpha)} \int_a^t (t-s)^{n-\alpha-1} h^n(s) ds.$$

Where  $n = [\alpha] + 1$

Noticeably, Caputo's derivative of a constant is equal to zero.

**Note 2.5** Now we need to note that  $\exists$  hookup between R-L and Caputo's fractional derivative of order  $\alpha$

$$\begin{aligned} ({}^c D^\alpha h)(t) &= \frac{1}{\Gamma(n-\alpha)} \int_{t_0}^t \frac{h^n(s)}{(t-s)^{\alpha+1-n}} ds = D^\alpha h(t) - \sum_{i=0}^{n-1} \frac{h^i(t_0)}{\Gamma(i-\alpha+1)} (t-t_0)^{i-\alpha} \\ &= D^\alpha \left[ h(t) - \sum_{i=0}^{n-1} \frac{h^i(t_0)}{i!} (t-t_0)^i \right], \quad t > t_0, \quad n-1 < \alpha < n \end{aligned}$$

**Theorem 2.6** (Krasnoselskii Fixed Point Theorem) [16] Let  $B$  is a real Banach space in  $X$ , be a bounded, closed and convex and let  $\mathbb{T}_1$  and  $\mathbb{T}_2$  be operators on  $B$  satisfying the following conditions let  $s \in B$ .

- $\mathbb{T}_1(s) + \mathbb{T}_2(s) \subset B$
- $\mathbb{T}_1$  is a strict contraction on  $B$ , (i. e.), there exists a  $l \in [a, b]$  such that  $\|\mathbb{T}_1(u) - \mathbb{T}_2(v)\| \leq l \|u - v\| \quad \forall u, v \in B$
- $\mathbb{T}_2$  is continuous on  $B$  and  $\mathbb{T}_2$  is relatively compact subset of  $X$ .  
Then there exists a  $y \in B$  such that  $\mathbb{T}_1 y + \mathbb{T}_2 y = y$ .

### 3 Existence Results

Let  $I_0 = [t_0, t_0 + \lambda]$ ,

$$A(\lambda, \vartheta) = \left\{ u \in C([t_0 + k, t_0 + \lambda], \mathbb{R}^n) \mid u_{t_0} = \theta, \sup_{t_0 \leq t \leq t_0 + \lambda} |u(t) - \theta(0)| \leq \rho \right\}$$

Where  $\lambda, \rho$  are positive constants.

To Prove our main result we need the following assumptions

[A1] The function  $g(t, \phi, \mathfrak{D}\phi)$  is measurable with respect to  $t$  on  $I_0$ ,

[A2] The function  $g(t, \phi, \mathfrak{D}\phi)$  is continuous with respect to  $\phi$  on  $C([-k, 0], \mathbb{R}^n)$ ,

[A3] Let us define a continuous function  $f \in (C[a, b] \times \mathfrak{R} \times \mathfrak{R}, \mathfrak{R})$  and  $u \in C[a, b]$  and there exists a positive constants  $\tau_1, \tau_2$  and such that

$$\|f(t, u_1, v_1) - f(t, u_2, v_2)\| \leq \tau_1 (\|u_1 - u_2\| + \|v_1 - v_2\|)$$

for each  $u_1, u_2, v_1, v_2$  in  $Y$ ,  $\tau_2 = \max_{t \in \mathbb{R}} \|f(t, 0, 0)\|$  and  $\tau = \max\{\tau_1, \tau_2\}$ . Let  $Y = C[\mathbb{R}, X]$  be the set of continuous functions on  $\mathbb{R}$  with in the Banach space  $X$  values.

[A4] Let us define a continuous function  $g \in (C[a, b] \times \mathfrak{R} \times \mathfrak{R}, \mathfrak{R})$  and  $u \in C[a, b]$  and there exists a positive constants  $\mathfrak{P}_1, \mathfrak{P}_2$  and such that

$$\|g(t, u_1, v_1) - g(t, u_2, v_2)\| \leq \mathfrak{P}_1 (\|u_1 - u_2\| + \|v_1 - v_2\|)$$

For each  $u_1, u_2, v_1, v_2$  in  $Y$ ,  $\mathfrak{P}_2 = \max_{t \in \mathbb{R}} \|g(t, 0, 0)\|$  and  $\mathfrak{P} = \max\{\mathfrak{P}_1, \mathfrak{P}_2\}$ . Let  $Y = C[\mathbb{R}, X]$  be the set of continuous functions on  $\mathbb{R}$  with in the Banach space  $X$  values.

[A5] Let  $u' \in C[a, b]$  satisfy the Lipschitz condition. i.e., There exists a positive constants  $\wp_1, \wp_2$  and  $\wp$  such that

$$\|\mathfrak{D}(t, u) - \mathfrak{D}(t, v)\| \leq \wp_1 (\|u - v\|),$$

for all  $u, v$  in  $Y$ .  $\wp_2 = \max_{t \in D} \|\mathfrak{D}(t, 0)\|$  and  $\wp = \max\{\wp_1, \wp_2\}$ .

[A6]  $\exists \varepsilon_1 \in (0, \alpha)$  and a real valued function  $\mathfrak{J}(t) \in \mathfrak{L}^{\varepsilon_1}(I_0)$  such that for any  $u \in A(\lambda, \rho)$ ,  $|g(t, u_t, \mathfrak{D}u_t)| \leq \mathfrak{d}(t)$  for  $t \in I_0$ , where  $\mathfrak{B}(t) = \tau + \wp t$  and  $\mathfrak{d}(t) = \mathfrak{P} + \wp t$ .

[A7] For any  $u \in A(\lambda, \vartheta)$ ,  $f(t, u_t, \mathfrak{D}u_t) = f_1(t, u_t, \mathfrak{D}u_t) + f_2(t, u_t, \mathfrak{D}u_t)$ ,

[A8] The function  $f_1$  is continuous and for any  $u_1, u_2 \in A(\lambda, \vartheta), t \in (0,1)$ , by using the assumption (A4) and (A5) we have  $\|f_1(t, u_1, \mathcal{D}u_1) - f_1(t, u_2, \mathcal{D}u_2)\| \leq [\tau + \wp t]\|u_1 - u_2\|$ . Take  $\mathfrak{B}$  is  $\tau + \wp t$ .

[A9] The function  $f_2$  is bounded and it's completely continuous for any  $\mathcal{E}$  in  $A(\lambda, \vartheta)$ , the equicontinuous set  $\{t \rightarrow f_2(t, u_t, \mathcal{D}u_t): u \in \mathcal{E}\}$  in  $C(I_0, \mathbb{R}^n)$ .

**Lemma 3.1** If (A3) - (A5) are satisfied, then the estimate  $\|\mathcal{D}u(t)\| \leq t(\wp_1\|u\| + \wp_2)$ ,  $\|\mathcal{D}u(t) - \mathcal{D}v(t)\| \leq \wp t\|u-v\|$  are satisfied for any  $t \in \mathbb{R}$  and  $u, v \in Y$ .

**Lemma 3.2** If (A1) - (A6) are satisfied and  $\exists \lambda \in (0, a)$  and  $\vartheta \in (0, \infty)$  then the IVP of (2) is equivalent to given equation for  $t \in (t_0, t_0 + \lambda]$

$$\begin{cases} u(t) = \varphi(0) - f(t_0, \varphi, \mathcal{D}\varphi) + f(t, u_t, \mathcal{D}u_t) + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} g(s, u_s, \mathcal{D}u_s) ds, & t \in t_0 \\ u_{t_0} = \varphi \end{cases} \quad (3)$$

**Proof:** It is clear that by the assumption (A1) and (A2) in the interval  $I_0$  the function  $g(t, u_t, \mathcal{D}u_t)$  is Lebesgue measurable and  $(t-s)^{\alpha-1} \in \mathcal{L}^{1-\varepsilon_1}([t_0, t])$  for  $t \in t_0$ . By using assumption (A6) and Holders inequality we conclude that the  $(t-s)^{\alpha-1}g(s, u_s, \mathcal{D}u_s)$  is Lebesgue integrable in regard to  $s \in [t_0, t] \forall t \in I_0$  &  $u \in A(\lambda, \vartheta)$ ,

$$\int_{t_0}^t |(t-s)^{\alpha-1}g(s, u_s, \mathcal{D}u_s)| ds \leq \|(t-s)^{\alpha-1}\|_{\mathcal{L}^{1-\varepsilon_1}(I_0)} \|\mathfrak{d}(t)\|_{\mathcal{L}^{\frac{1}{\varepsilon_1}}(I_0)} \quad (4)$$

Where  $\|G\|_{\mathcal{L}^p(J)} = (\int_J |G(t)|^p dt)^{\frac{1}{p}}$  for all  $\mathcal{L}^p$ - integrable function  $G: J \rightarrow \mathbb{R}$ .

Sympathetic to Definition 2.1 and 2.3 obviously that the initial value problem of (2) clarification is  $u$  and it is a solution of equation (3).

Besides, if equation (3) is certain, then  $\forall t \in (t_0, t_0 + \lambda]$ ,

$$\begin{aligned} ({}^c D^\alpha)(u(t) - f(t, u_t, \mathcal{D}u_t)) &= ({}^c D^\alpha) \left[ \varphi(0) - f(t_0, \varphi, \mathcal{D}\varphi) + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} g(s, u_s, \mathcal{D}u_s) ds \right] \\ &= ({}^c D^\alpha) \left[ \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} g(s, u_s, \mathcal{D}u_s) ds \right] \\ &= ({}^c D^\alpha)(I^\alpha g(t, u_t, \mathcal{D}u_t)) \\ &= D^\alpha(I^\alpha g(t, u_t, \mathcal{D}u_t)) - [I^\alpha g(t, u_t, \mathcal{D}u_t)]_{t=t_0} \frac{(t-t_0)^{-\alpha}}{\Gamma(1-\alpha)} \\ &= g(t, u_t, \mathcal{D}u_t) - [I^\alpha g(t, u_t, \mathcal{D}u_t)]_{t=t_0} \frac{(t-t_0)^{-\alpha}}{\Gamma(1-\alpha)} \end{aligned}$$

Sympathetic to (4) we notice that  $[I^\alpha g(t, u_t, \mathcal{D}u_t)]_{t=t_0} = 0$  which aid that

$({}^c D^\alpha)(u(t) - f(t, u_t, \mathcal{D}u_t)) = g(t, u_t, \mathcal{D}u_t)$ ,  $t \in (t_0, t_0 + \lambda]$ . This completes the proof.

**Theorem 3.3** If (A1)-(A9) are satisfied and assume that  $\exists \lambda \in (0, a)$  and  $\vartheta \in (0, \infty)$ . Then the initial value problem of equation (2) has unique solution on  $[t_0, t_0 + \mu]$  for some +ve number  $\mu$ .

**Proof:** Corresponding to the assumption (A7), and system (3) is comparable to the consecutive system

$$\begin{cases} u(t) = \varphi(0) - f_1(t_0, \varphi, \mathcal{D}\varphi) - f_2(t_0, \varphi, \mathcal{D}\varphi) + f_1(t, u_t, \mathcal{D}u_t) + f_2(t, u_t, \mathcal{D}u_t) \\ \quad + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} g(s, u_s, \mathcal{D}u_s) ds \\ u_{t_0} = \varphi \end{cases}$$

Now  $\varphi^* \in A(\lambda, \vartheta)$  be defined as  $\varphi_{t_0}^* = \varphi$ ,  $\varphi^*(t_0 + t) = \varphi(0) \forall t \in [0, \lambda]$ . If the initial value problem (2) has  $u$  is a solution, let  $u(t_0 + t) = \varphi^*(t_0 + t) + \mathfrak{x}(t)$ ,  $t \in [-k, \lambda]$ , then we have  $u_{t_0+t} = \varphi_{t_0+t}^* + \mathfrak{x}_t$ ,  $t \in [0, \lambda]$ . So  $\mathfrak{x}$  satisfies the equation.

$$\begin{aligned} \mathfrak{x}(t) &= -f_1(t_0, \varphi, \mathcal{D}\varphi) - f_2(t_0, \varphi, \mathcal{D}\varphi) + f_1(t_0 + t, \mathfrak{x}_t + \varphi_{t_0+t}^*, \mathcal{D}(\mathfrak{x}_t + \varphi_{t_0+t}^*)) \\ &\quad + f_2(t_0 + t, \mathfrak{x}_t + \varphi_{t_0+t}^*, \mathcal{D}(\mathfrak{x}_t + \varphi_{t_0+t}^*)) \\ &\quad + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} g(t_0 + s, \mathfrak{x}_s + \varphi_{t_0+s}^*, \mathcal{D}(\mathfrak{x}_s + \varphi_{t_0+s}^*)) ds \end{aligned} \quad (5)$$

Whereas  $f_1, f_2$  are continuous and  $u_t$  is continuous in  $t, \exists \lambda' > 0$ , when  $0 < t < \lambda'$

$$\left| f_1(t_0 + t, \mathfrak{x}_t + \varphi_{t_0+t}^*, \mathcal{D}(\mathfrak{x}_t + \varphi_{t_0+t}^*)) - f_1(t_0, \varphi, \mathcal{D}\varphi) \right| < \frac{\xi}{4} \quad (6)$$

and

$$\left| f_2(t_0 + t, \mathfrak{x}_t + \varphi_{t_0+t}^*, \mathcal{D}(\mathfrak{x}_t + \varphi_{t_0+t}^*)) - f_2(t_0, \varphi, \mathcal{D}\varphi) \right| < \frac{\xi}{4} \quad (7)$$

$$\text{Prefer } \mu = \left\{ \lambda, \lambda', \left( \frac{\vartheta \Gamma(\alpha)(1+\gamma)^{1-\varepsilon_1}}{2G} \right)^{\frac{1}{(1+\gamma)(1-\varepsilon_1)}} \right\} \tag{8}$$

Where  $\gamma = \frac{\alpha-1}{1-\varepsilon_1} \in (-1,0)$  &  $G = \|\mathfrak{d}(t)\|_{\frac{1}{\mathfrak{Q}^{\varepsilon_1}(I_0)}}$

Define  $\mathbb{B}(\mu, \vartheta) = \{u \in C([-k, \mu], \mathbb{R}^n) | u(s) = 0 \text{ for } s \in [-k, 0] \text{ and } \|u\| \leq \vartheta\}$  and it is closed, convex and bounded subset of  $C([-k, \mu], \mathbb{R}^n)$ .

Now we define the operator  $\mathcal{T}_1$  and  $\mathcal{T}_2$  as

$$\begin{aligned} \mathcal{T}_1 u(t) &= \begin{cases} -f_1(t_0, \varphi, \mathfrak{D}\varphi) + f_1(t_0 + t, u_t + \varphi_{t_0+t}^*, \mathfrak{D}(u_t + \varphi_{t_0+t}^*)), & t \in [0, \mu] \\ 0, & t \in [-k, 0] \end{cases} \\ \mathcal{T}_2 u(t) &= \begin{cases} -f_2(t_0, \varphi, \mathfrak{D}\varphi) + f_2(t_0 + t, u_t + \varphi_{t_0+t}^*, \mathfrak{D}(u_t + \varphi_{t_0+t}^*)) \\ \quad + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} g(t_0 + s, u_s + \varphi_{t_0+s}^*, \mathfrak{D}(u_s + \varphi_{t_0+s}^*)) ds, & t \in [0, \mu] \\ 0, & t \in [-k, 0] \end{cases} \end{aligned}$$

The operator equation has a solution  $u \in \mathbb{B}(\mu, \vartheta) \iff$  the equation (5) has solution  $u = \mathcal{T}_1 u + \mathcal{T}_2 u$ . (9)

Hence (2) has solution  $u(t_0 + t) = \mathfrak{x}_t + \varphi_{t_0+t}^*$  on  $[0, \mu]$ .

Therefore  $\exists$  a existence solution of IVP (2) and unique fixed point in  $\mathbb{B}(\mu, \vartheta)$  which is equivalent to the equation (9).

Now we prove that  $\mathcal{T}_1 + \mathcal{T}_2$  has a unique fixed point in  $\mathbb{B}(\mu, \vartheta)$

**Step 1:**  $\mathcal{T}_1 u + \mathcal{T}_2 u \in \mathbb{B}(\mu, \vartheta)$  for all pair  $\eta, \mathfrak{z} \in \mathbb{B}(\mu, \vartheta)$ .

For all  $\eta, \mathfrak{z} \in \mathbb{B}(\mu, \vartheta), \mathcal{T}_1 \eta + \mathcal{T}_2 \mathfrak{z} \in C([-k, \mu], \mathbb{R}^n)$ . As well as it is trivial that  $(\mathcal{T}_1 \eta + \mathcal{T}_2 \mathfrak{z})(t) = 0 \quad t \in [-k, 0]$

Furthermore for  $t \in [0, \mu]$ , by the equation (6)-(8) and the assumption (A6) we have

$$\begin{aligned} |(\mathcal{T}_1 \eta + \mathcal{T}_2 \mathfrak{z})(t)| &\leq \left| -f_1(t_0, \varphi, \mathfrak{D}\varphi) + f_1(t_0 + t, \eta_t + \varphi_{t_0+t}^*, \mathfrak{D}(\eta_t + \varphi_{t_0+t}^*)) \right| \\ &\quad + \left| -f_2(t_0, \varphi, \mathfrak{D}\varphi) + f_2(t_0 + t, \mathfrak{z}_t + \varphi_{t_0+t}^*, \mathfrak{D}(\mathfrak{z}_t + \varphi_{t_0+t}^*)) \right| \\ &\quad + \frac{1}{\Gamma(\alpha)} \int_0^t \left| (t-s)^{\alpha-1} g(t_0 + s, \mathfrak{z}_s + \varphi_{t_0+s}^*, \mathfrak{D}(\mathfrak{z}_s + \varphi_{t_0+s}^*)) \right| ds \\ &\leq \frac{2\vartheta}{4} + \frac{1}{\Gamma(\alpha)} \left( \int_0^t (t-s)^{\frac{\alpha-1}{1-\varepsilon_1}} ds \right)^{1-\varepsilon} \left( \int_{t_0}^{t_0+\lambda} (\mathfrak{d}(s))^{\frac{1}{\varepsilon_1}} \right)^{\varepsilon_1} \\ &\leq \frac{\vartheta}{2} + \frac{g\mu^{(1+\gamma)(1-\varepsilon_1)}}{\Gamma(\alpha)(1+\gamma)^{1-\varepsilon_1}} \leq \vartheta \end{aligned}$$

$$\begin{aligned} \therefore \|\mathcal{T}_1 \eta + \mathcal{T}_2 \mathfrak{z}\| &= \sup_{t \in [0, \mu]} |(\mathcal{T}_1 \eta)(t) + (\mathcal{T}_2 \mathfrak{z})(t)| \leq \vartheta \\ &\implies \mathcal{T}_1 \eta + \mathcal{T}_2 \mathfrak{z} \in \mathbb{B}(\mu, \vartheta) \end{aligned}$$

**Step: 2**  $\mathcal{T}_1$  is a contraction on  $\mathbb{B}(\mu, \vartheta)$

For all  $u', u'' \in \mathbb{B}(\mu, \vartheta), u'_t + \varphi_{t_0+t}^* \in \mathbb{A}(\lambda, \vartheta)$  by using (A8) we attain

$$\begin{aligned} |\mathcal{T}_1 u'(t) - \mathcal{T}_1 u''(t)| &= \left| f_1(t_0 + t, u'_t + \varphi_{t_0+t}^*, \mathfrak{D}(u'_t + \varphi_{t_0+t}^*)) - f_1(t_0 + t, u''_t + \varphi_{t_0+t}^*, \mathfrak{D}(u''_t + \varphi_{t_0+t}^*)) \right| \\ &\leq \mathfrak{W} \|u' - u''\|, \end{aligned}$$

$$\implies |\mathcal{T}_1 u' - \mathcal{T}_1 u''| \leq \mathfrak{W} \|u' - u''\|$$

$\therefore \mathcal{T}_1$  is a contraction on  $\mathbb{B}(\mu, \vartheta)$ .

**Step: 3** Here we prove that  $\mathcal{T}_2$  is a completely continuous operator.

Let

$$\begin{aligned} \mathbb{T}_1 u(t) &= \begin{cases} -f_2(t_0, \varphi, \mathfrak{D}\varphi) + f_2(t_0 + t, u_t + \varphi_{t_0+t}^*, \mathfrak{D}(u_t + \varphi_{t_0+t}^*)) & t \in [0, \mu] \\ 0, & t \in [-k, 0] \end{cases} \quad \text{and} \\ \mathbb{T}_2 u(t) &= \begin{cases} \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} g(t_0 + s, u_s + \varphi_{t_0+s}^*, \mathfrak{D}(u_s + \varphi_{t_0+s}^*)) ds & t \in [0, \mu] \\ 0, & t \in [-k, 0] \end{cases} \end{aligned}$$

Which means  $\mathcal{T}_2 = \mathbb{T}_1 + \mathbb{T}_2$

We know that the function  $f_2$  is completely continuous and  $\mathbb{T}_1$  is continuous and  $\{\mathbb{T}_1 u : u \in \mathbb{B}(\mu, \vartheta)\}$  which is uniformly bounded. By the assumption (A9) we desist that the operator  $\mathbb{T}_1$  is completely continuous.

Besides for all  $t \in [0, \mu]$ , we have

$$|\mathcal{T}_2 u(t)| \leq \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} |g(t_0 + s, \mathfrak{x}_s + \varphi_{t_0+s}^*, \mathfrak{D}(\mathfrak{x}_s + \varphi_{t_0+s}^*))| ds$$

$$\begin{aligned} &\leq \frac{1}{\Gamma(\alpha)} \left( \int_0^t (t-s)^{\frac{\alpha-1}{1-\varepsilon_1}} ds \right)^{1-\varepsilon} \left( \int_{t_0}^{t_0+\lambda} (\mathfrak{D}(s))^{\frac{1}{\varepsilon_1}} \right)^{\varepsilon_1} \\ &\leq \frac{\mathcal{G}\mu^{(1+\gamma)(1-\varepsilon_1)}}{\Gamma(\alpha)(1+\gamma)^{1-\varepsilon_1}} \end{aligned}$$

Thus  $\{\mathcal{T}_2 u : u \in \mathbb{B}(\mu, \vartheta)\}$  is uniformly bounded.

Next, we prove that  $\{\mathcal{T}_2 u : u \in \mathbb{B}(\mu, \vartheta)\}$  is equicontinuous. For all  $0 \leq t_1 \leq t_2 \leq \mu$  and  $u \in \mathbb{B}(\mu, \vartheta)$

$$\begin{aligned} &|\mathcal{T}_2 u(t_2) - \mathcal{T}_2 u(t_1)| \\ &= \left| \frac{1}{\Gamma(\alpha)} \int_0^{t_1} [(t_2-s)^{\alpha-1} - (t_1-s)^{\alpha-1}] g(t_0+s, u_s + \varphi_{t_0+s}^*, \mathfrak{D}(u_s + \varphi_{t_0+s}^*)) ds \right. \\ &\quad \left. + \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2-s)^{\alpha-1} g(t_0+s, u_s + \varphi_{t_0+s}^*, \mathfrak{D}(u_s + \varphi_{t_0+s}^*)) ds \right| \\ &\leq \frac{1}{\Gamma(\alpha)} \int_0^{t_1} |(t_2-s)^{\alpha-1} - (t_1-s)^{\alpha-1}| |g(t_0+s, u_s + \varphi_{t_0+s}^*, \mathfrak{D}(u_s + \varphi_{t_0+s}^*))| ds \\ &\quad + \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2-s)^{\alpha-1} |g(t_0+s, u_s + \varphi_{t_0+s}^*, \mathfrak{D}(u_s + \varphi_{t_0+s}^*))| ds \\ &\leq \frac{\mathcal{G}}{\Gamma(\alpha)} \left( \int_0^{t_1} [(t_2-s)^{\alpha-1} - (t_1-s)^{\alpha-1}]^{\frac{1}{1-\varepsilon_1}} \right)^{1-\varepsilon_1} + \frac{\mathcal{G}}{\Gamma(\alpha)} \left( \int_{t_1}^{t_2} [(t_2-s)^{\alpha-1}]^{\frac{1}{1-\varepsilon_1}} \right)^{1-\varepsilon_1} \\ &\leq \frac{\mathcal{G}}{\Gamma(\alpha)} \left( \int_0^{t_1} (t_2-s)^\gamma - (t_1-s)^\gamma \right)^{1-\varepsilon_1} + \frac{\mathcal{G}}{\Gamma(\alpha)} \left( \int_{t_1}^{t_2} (t_2-s)^\gamma \right)^{1-\varepsilon_1} \\ &\leq \frac{\mathcal{G}}{\Gamma(\alpha)(1+\gamma)^{(1-\varepsilon_1)}} (t_1^{1+\gamma} - t_2^{1+\gamma} + (t_2-t_1)^{1+\gamma})^{1-\varepsilon_1} + \frac{\mathcal{G}}{\Gamma(\alpha)(1+\gamma)^{1-\varepsilon_1}} (t_2-t_1)^{(1+\gamma)(1-\varepsilon_1)} \\ &\leq \frac{2\mathcal{G}}{\Gamma(\alpha)(1+\gamma)^{(1-\varepsilon_1)}} (t_2-t_1)^{(1+\gamma)(1-\varepsilon_1)}, \end{aligned}$$

$\therefore \mathcal{T}_2$  is equicontinuous, Furthermore, we know that  $\mathcal{T}_2$  is continuous. Thus  $\mathcal{T}_2$  is completely continuous operator. Also  $\mathcal{T}_2 = \mathbb{T}_1 + \mathbb{T}_2$  is completely continuous operator. By using the theorem (2.6)  $\mathcal{T}_1 + \mathcal{T}_2$  has unique fixed point on  $\mathbb{B}(\mu, \vartheta)$ .

Suppose that  $f_1 = 0$ , we get the following result

**Theorem: 3.4** If (A1)-(A6) satisfied such that  $\exists \lambda \in (0, a)$  and  $\vartheta \in (0, \infty)$  and

**[A10]** The function  $f$  is continuous and for any  $u_1, u_2 \in A(\lambda, \vartheta), t \in (0, 1)$ , by using the assumption (A4) and (A5) we have  $\|f(t, u_1, \mathfrak{D}u_1) - f(t, u_2, \mathfrak{D}u_2)\| \leq \mathfrak{B}\|u_1 - u_2\|$

Then the given system(2) has atleast one solution on the interval  $[t_0, t_0 + \mu]$  for some positive integer  $\mu$ .

If suppose that  $f_2 = 0$ , we get the following result. By Theorem (2.6)  $\mathcal{T}_1 + \mathcal{T}_2$  has unique fixed point on  $\mathbb{B}(\mu, \vartheta)$ .

Suppose that  $f_1 = 0$ , we get the following result

**Theorem: 3.5** If (A1)-(A6) satisfied such that  $\exists \lambda \in (0, a)$  and  $\vartheta \in (0, \infty)$  and

**[A1]** The function  $f$  is continuous and for any  $u_1, u_2 \in A(\lambda, \vartheta), t \in (0, 1)$ , by using the assumption (A4) and (A5) we have  $\|f(t, u_1, \mathfrak{D}u_1) - f(t, u_2, \mathfrak{D}u_2)\| \leq \mathfrak{B}\|u_1 - u_2\|$

Then the given system (2) has atleast one solution on the interval  $[t_0, t_0 + \mu]$  for some positive integer  $\mu$ .

## REFERENCES

- [1] A.A. Kilbas, H.M. Srivastava, J.J. Trujillo, Theory and Applications of Fractional Differential Equations, in: North-Holland Mathematics Studies, vol. 204, Elsevier, Amsterdam, 2006.
- [2] Bagley, Ronald L., and R. A. Calico, Fractional order state equations for the control of visco elastically damped structures, Journal of Guidance, Control, and Dynamics 14.2 (1991): 304-311.
- [3] Frunzo, Luigi, Modeling biological systems with an improved fractional Gompertz law, Communications in Nonlinear Science and Numerical Simulation 74 (2019): 260-267.
- [4] Ibrahim, Rabha W, A medical image enhancement based on generalized class of fractional partial differential equations, Quantitative Imaging in Medicine and Surgery 12.1 (2022): 172.
- [5] I. Podlubny, Fractional Differential Equations, Academic Press, New York, 1993.
- [6] Kassim, Mohammed D, Nasser-eddine Tatar. "A neutral fractional Halanay inequality and application to a Cohen-Grossberg neural network system." Mathematical Methods in the Applied Sciences 44.13 (2021): 10460-10476.
- [7] Kumar, Devendra, Jagdev Singh, eds, Fractional calculus in medical and health science. CRC Press, 2020.
- [8] Lorenzo, Carl F., and Tom T. Hartley. The fractional trigonometry: With applications to fractional differential equations and science. John Wiley and Sons, 2016.
- [9] M. Benchohra, J. Henderson, S.K. Ntouyas, A. Ouahab, Existence results for fractional order functional differential equations with infinite delay, J. Math. Anal. Appl., 338 (2008), pp. 1340-1350.

- [10] Rahimy, Mehdi, Applications of fractional differential equations, *Applied Mathematical Sciences* 4.50 (2010): 2453-2461.
- [11] Singh, Harendra, Devendra Kumar, Dumitru Baleanu, eds. *Methods of mathematical modelling: fractional differential equations*. CRC Press, 2019.
- [12] Srivastava, H. M., Dumitru Baleanu, and Changpin Li. "Preface: recent advances in fractional dynamics." *Chaos: An Interdisciplinary Journal of Nonlinear Science* 26.8 (2016): 084101.
- [13] Sun, H.; Zhang Y, Baleanuac, D.,Chen, We, Y, Chen Y. A new collection of real world applications of fractional calculus in science and engineering. *Commun. Nonlinear Sci. Numer. Simul.* 2018, 64, 213–231.
- [14] Tripathi, D, O. Anwar Bég. "Mathematica numerical simulation of peristaltic biophysical transport of a fractional viscoelastic fluid through an inclined cylindrical tube." *Computer Methods in Biomechanics and Biomedical Engineering* 18.15 (2015): 1648-1657.
- [15] U. Cakan, I. Ozdemir, An application of Krasnoselskii fixed point theorem to some nonlinear functional integral equations, *Nevsehir Bilim ve Teknoloji Dergisi* 3(2)(2014), 66-73.
- [16] Xu, Mingyu, Wenchang Tan. "Intermediate processes and critical phenomena: Theory, method and progress of fractional operators and their applications to modern mechanics." *Science in China Series G* 49.3 (2006): 257-272.